**Introduction**

XC4000 Series high-performance, high-capacity Field Programmable Gate Arrays (FPGAs) provide the benefits of custom CMOS VLSI, while avoiding the initial cost, long development cycle, and inherent risk of a conventional masked gate array.

The result of thirteen years of FPGA design experience and feedback from thousands of customers, these FPGAs combine architectural versatility, on-chip Select-RAM memory with edge-triggered and dual-port modes, increased speed, abundant routing resources, and new, sophisticated software to achieve fully automated implementation of complex, high-density, high-performance designs.

The XC4000E and XC4000X Series currently have 20 members, as shown in Table 2.

**Note:** All functionality in low-voltage families is the same as in the corresponding 5-Volt family, except where numerical references are made to timing or power.
**Description**

XC4000 Series devices are implemented with a regular, flexible, programmable architecture of Configurable Logic Blocks (CLBs), interconnected by a powerful hierarchy of versatile routing resources, and surrounded by a perimeter of programmable Input/Output Blocks (IOBs). They have generous routing resources to accommodate the most complex interconnect patterns.

The devices are customized by loading configuration data into internal memory cells. The FPGA can either actively read its configuration data from an external serial or byte-parallel PROM (master modes), or the configuration data can be written into the FPGA from an external device (slave and peripheral modes).

XC4000 Series FPGAs are supported by powerful and sophisticated software, covering every aspect of design from schematic or behavioral entry, floorplanning, simulation, automatic block placement and routing of interconnects, to the creation, downloading, and readback of the configuration bit stream.

Because Xilinx FPGAs can be reprogrammed an unlimited number of times, they can be used in innovative designs where hardware is changed dynamically, or where hardware must be adapted to different user applications.

FPGAs are ideal for shortening design and development cycles, and also offer a cost-effective solution for production rates well beyond 5,000 systems per month. For lowest high-volume unit cost, a design can first be implemented in the XC4000E or XC4000X, then migrated to one of Xilinx’ compatible HardWire mask-programmed devices.

**Taking Advantage of Reconfiguration**

FPGA devices can be reconfigured to change logic function while resident in the system. This capability gives the system designer a new degree of freedom not available with any other type of logic.

Hardware can be changed as easily as software. Design updates or modifications are easy, and can be made to products already in the field. An FPGA can even be reconfigured dynamically to perform different functions at different times.

Reconfigurable logic can be used to implement system self-diagnostics, create systems capable of being reconfigured for different environments or operations, or implement multi-purpose hardware for a given application. As an added benefit, using reconfigurable FPGA devices simplifies hardware design and debugging and shortens product time-to-market.

---

**Table 2: XC4000E and XC4000X Series Field Programmable Gate Arrays**

<table>
<thead>
<tr>
<th>Device</th>
<th>Logic Cells</th>
<th>Max Logic Gates (No RAM)</th>
<th>Max. RAM Bits (No Logic)</th>
<th>Typical Gate Range (Logic and RAM)*</th>
<th>CLB Matrix</th>
<th>Total CLBs</th>
<th>Number of Flip-Flops</th>
<th>Max. User I/O</th>
</tr>
</thead>
<tbody>
<tr>
<td>XC4003E</td>
<td>238</td>
<td>3,000</td>
<td>3,200</td>
<td>2,000 - 5,000</td>
<td>10 x 10</td>
<td>100</td>
<td>360</td>
<td>80</td>
</tr>
<tr>
<td>XC4005E/XL</td>
<td>466</td>
<td>5,000</td>
<td>6,272</td>
<td>3,000 - 9,000</td>
<td>14 x 14</td>
<td>196</td>
<td>616</td>
<td>112</td>
</tr>
<tr>
<td>XC4006E</td>
<td>608</td>
<td>6,000</td>
<td>8,192</td>
<td>4,000 - 12,000</td>
<td>16 x 16</td>
<td>256</td>
<td>768</td>
<td>128</td>
</tr>
<tr>
<td>XC4008E</td>
<td>770</td>
<td>8,000</td>
<td>10,368</td>
<td>6,000 - 15,000</td>
<td>18 x 18</td>
<td>324</td>
<td>936</td>
<td>144</td>
</tr>
<tr>
<td>XC4010E/XL</td>
<td>950</td>
<td>10,000</td>
<td>12,800</td>
<td>7,000 - 20,000</td>
<td>20 x 20</td>
<td>400</td>
<td>1,120</td>
<td>160</td>
</tr>
<tr>
<td>XC4013E/XL</td>
<td>1368</td>
<td>13,000</td>
<td>18,432</td>
<td>10,000 - 30,000</td>
<td>24 x 24</td>
<td>576</td>
<td>1,536</td>
<td>192</td>
</tr>
<tr>
<td>XC4020E/XL</td>
<td>1862</td>
<td>20,000</td>
<td>25,088</td>
<td>13,000 - 40,000</td>
<td>28 x 28</td>
<td>784</td>
<td>2,016</td>
<td>224</td>
</tr>
<tr>
<td>XC4025E</td>
<td>2432</td>
<td>25,000</td>
<td>32,768</td>
<td>15,000 - 45,000</td>
<td>32 x 32</td>
<td>1,024</td>
<td>2,560</td>
<td>256</td>
</tr>
<tr>
<td>XC4028EX/XL</td>
<td>2432</td>
<td>28,000</td>
<td>32,768</td>
<td>18,000 - 50,000</td>
<td>32 x 32</td>
<td>1,024</td>
<td>2,560</td>
<td>256</td>
</tr>
<tr>
<td>XC4036EX/XL</td>
<td>3078</td>
<td>36,000</td>
<td>41,472</td>
<td>22,000 - 65,000</td>
<td>36 x 36</td>
<td>1,296</td>
<td>3,168</td>
<td>288</td>
</tr>
<tr>
<td>XC4044XL</td>
<td>3800</td>
<td>44,000</td>
<td>51,200</td>
<td>27,000 - 80,000</td>
<td>40 x 40</td>
<td>1,600</td>
<td>3,840</td>
<td>320</td>
</tr>
<tr>
<td>XC4052XL</td>
<td>4598</td>
<td>52,000</td>
<td>61,952</td>
<td>33,000 - 100,000</td>
<td>44 x 44</td>
<td>1,936</td>
<td>4,576</td>
<td>352</td>
</tr>
<tr>
<td>XC4062XL</td>
<td>5472</td>
<td>62,000</td>
<td>73,728</td>
<td>40,000 - 130,000</td>
<td>48 x 48</td>
<td>2,304</td>
<td>5,376</td>
<td>384</td>
</tr>
<tr>
<td>XC4085XL</td>
<td>7448</td>
<td>85,000</td>
<td>100,352</td>
<td>55,000 - 180,000</td>
<td>56 x 56</td>
<td>3,136</td>
<td>7,168</td>
<td>448</td>
</tr>
</tbody>
</table>

* Max values of Typical Gate Range include 20-30% of CLBs used as RAM.
XC4000E and XC4000X Series Compared to the XC4000

For readers already familiar with the XC4000 family of Xilinx Field Programmable Gate Arrays, the major new features in the XC4000 Series devices are listed in this section. The biggest advantages of XC4000E and XC4000X devices are significantly increased system speed, greater capacity, and new architectural features, particularly Select-RAM memory. The XC4000X devices also offer many new routing features, including special high-speed clock buffers that can be used to capture input data with minimal delay.

Any XC4000E device is pinout- and bitstream-compatible with the corresponding XC4000 device. An existing XC4000 bitstream can be used to program an XC4000E device. However, since the XC4000E includes many new features, an XC4000E bitstream cannot be loaded into an XC4000 device.

XC4000X Series devices are not bitstream-compatible with equivalent array size devices in the XC4000 or XC4000E families. However, equivalent array size devices, such as the XC4025, XC4025E, XC4028EX, and XC4028XL, are pinout-compatible.

**Improvements in XC4000E and XC4000X**

**Increased System Speed**

XC4000E and XC4000X devices can run at synchronous system clock rates of up to 80 MHz, and internal performance can exceed 150 MHz. This increase in performance over the previous families stems from improvements in both device processing and system architecture. XC4000 Series devices use a sub-micron multi-layer metal process. In addition, many architectural improvements have been made, as described below.

The XC4000XL family is a high performance 3.3V family based on 0.35µm SRAM technology and supports system speeds to 80 MHz.

**PCI Compliance**

XC4000 Series -2 and faster speed grades are fully PCI compliant. XC4000E and XC4000X devices can be used to implement a one-chip PCI solution.

**Carry Logic**

The speed of the carry logic chain has increased dramatically. Some parameters, such as the delay on the carry chain through a single CLB (T_{BYP}), have improved by as much as 50% from XC4000 values. See “Fast Carry Logic” on page 4-18 for more information.

**Select-RAM Memory: Edge-Triggered, Synchronous RAM Modes**

The RAM in any CLB can be configured for synchronous, edge-triggered, write operation. The read operation is not affected by this change to an edge-triggered write.

**Dual-Port RAM**

A separate option converts the 16x2 RAM in any CLB into a 16x1 dual-port RAM with simultaneous Read/Write.

The function generators in each CLB can be configured as either level-sensitive (asynchronous) single-port RAM, edge-triggered (synchronous) single-port RAM, edge-triggered (synchronous) dual-port RAM, or as combinatorial logic.

**Configurable RAM Content**

The RAM content can now be loaded at configuration time, so that the RAM starts up with user-defined data.

**H Function Generator**

In current XC4000 Series devices, the H function generator is more versatile than in the original XC4000. Its inputs can come not only from the F and G function generators but also from up to three of the four control input lines. The H function generator can thus be totally or partially independent of the other two function generators, increasing the maximum capacity of the device.

**IOB Clock Enable**

The two flip-flops in each IOB have a common clock enable input, which through configuration can be activated individually for the input or output flip-flop or both. This clock enable operates exactly like the EC pin on the XC4000 CLB. This new feature makes the IOBs more versatile, and avoids the need for clock gating.

**Output Drivers**

The output pull-up structure defaults to a TTL-like totem-pole. This driver is an n-channel pull-up transistor, pulling to a voltage one transistor threshold below Vcc, just like the XC4000 family outputs. Alternatively, XC4000 Series devices can be globally configured with CMOS outputs, with p-channel pull-up transistors pulling to Vcc. Also, the configurable pull-up resistor in the XC4000 Series is a p-channel transistor that pulls to Vcc, whereas in the original XC4000 family it is an n-channel transistor that pulls to a voltage one transistor threshold below Vcc.
Input Thresholds
The input thresholds of 5V devices can be globally configured for either TTL (1.2 V threshold) or CMOS (2.5 V threshold), just like XC2000 and XC3000 inputs. The two global adjustments of input threshold and output level are independent of each other. The XC4000XL family has an input threshold of 1.6V, compatible with both 3.3V CMOS and TTL levels.

Global Signal Access to Logic
There is additional access from global clocks to the F and G function generator inputs.

Configuration Pin Pull-Up Resistors
During configuration, the three mode pins, M0, M1, and M2, have weak pull-up resistors. For the most popular configuration mode, Slave Serial, the mode pins can thus be left unconnected.

The three mode inputs can be individually configured with or without weak pull-up or pull-down resistors after configuration.

The PROGRAM input pin has a permanent weak pull-up.

Soft Start-up
Like the XC3000A, XC4000 Series devices have “Soft Start-up.” When the configuration process is finished and the device starts up, the first activation of the outputs is automatically slew-rate limited. This feature avoids potential ground bounce when all outputs are turned on simultaneously. Immediately after start-up, the slew rate of the individual outputs is, as in the XC4000 family, determined by the individual configuration option.

XC4000 and XC4000A Compatibility
Existing XC4000 bitstreams can be used to configure an XC4000E device. XC4000A bitstreams must be recompiled for use with the XC4000E due to improved routing resources, although the devices are pin-for-pin compatible.

Additional Improvements in XC4000X Only

Increased Routing
New interconnect in the XC4000X includes twenty-two additional vertical lines in each column of CLBs and twelve new horizontal lines in each row of CLBs. The twelve “Quad Lines” in each CLB row and column include optional repowering buffers for maximum speed. Additional high-performance routing near the IOBs enhances pin flexibility.

Faster Input and Output
A fast, dedicated early clock sourced by global clock buffers is available for the IOBs. To ensure synchronization with the regular global clocks, a Fast Capture latch driven by the early clock is available. The input data can be initially loaded into the Fast Capture latch with the early clock, then transferred to the input flip-flop or latch with the low-skew global clock. A programmable delay on the input can be used to avoid hold-time requirements. See “IOB Input Signals” on page 4-21 for more information.

Latch Capability in CLBs
Storage elements in the XC4000X CLB can be configured as either flip-flops or latches. This capability makes the FPGA highly synthesis-compatible.

IOB Output MUX From Output Clock
A multiplexer in the IOB allows the output clock to select either the output data or the IOB clock enable as the output to the pad. Thus, two different data signals can share a single output pad, effectively doubling the number of device outputs without requiring a larger, more expensive package. This multiplexer can also be configured as an AND-gate to implement a very fast pin-to-pin path. See “IOB Output Signals” on page 4-24 for more information.

Additional Address Bits
Larger devices require more bits of configuration data. A daisy chain of several large XC4000X devices may require a PROM that cannot be addressed by the eighteen address bits supported in the XC4000E. The XC4000X Series therefore extends the addressing in Master Parallel configuration mode to 22 bits.
Detailed Functional Description

XC4000 Series devices achieve high speed through advanced semiconductor technology and improved architecture. The XC4000E and XC4000X support system clock rates of up to 80 MHz and internal performance in excess of 150 MHz. Compared to older Xilinx FPGA families, XC4000 Series devices are more powerful. They offer on-chip edge-triggered and dual-port RAM, clock enables on I/O flip-flops, and wide-input decoders. They are more versatile in many applications, especially those involving RAM. Design cycles are faster due to a combination of increased routing resources and more sophisticated software.

Basic Building Blocks

Xilinx user-programmable gate arrays include two major configurable elements: configurable logic blocks (CLBs) and input/output blocks (IOBs).

- CLBs provide the functional elements for constructing the user’s logic.
- IOBs provide the interface between the package pins and internal signal lines.

Three other types of circuits are also available:

- 3-State buffers (TBUFs) driving horizontal longlines are associated with each CLB.
- Wide edge decoders are available around the periphery of each device.
- An on-chip oscillator is provided.

Programmable interconnect resources provide routing paths to connect the inputs and outputs of these configurable elements to the appropriate networks.

The functionality of each circuit block is customized during configuration by programming internal static memory cells. The values stored in these memory cells determine the logic functions and interconnections implemented in the FPGA. Each of these available circuits is described in this section.

Configurable Logic Blocks (CLBs)

Configurable Logic Blocks implement most of the logic in an FPGA. The principal CLB elements are shown in Figure 2. Two 4-input function generators (F and G) offer unrestricted versatility. Most combinatorial logic functions need four or fewer inputs. However, a third function generator (H) is provided. The H function generator has three inputs. Either zero, one, or two of these inputs can be the outputs of F and G; the other input(s) are from outside the CLB. The CLB can, therefore, implement certain functions of up to nine variables, like parity check or expandable-identity comparison of two sets of four inputs.

Each CLB contains two storage elements that can be used to store the function generator outputs. However, the storage elements and function generators can also be used independently. These storage elements can be configured as flip-flops in both XC4000E and XC4000X devices; in the XC4000X they can optionally be configured as latches. DIN can be used as a direct input to either of the two storage elements. H1 can drive the other through the H function generator. Function generator outputs can also drive two outputs independent of the storage element outputs. This versatility increases logic capacity and simplifies routing.

Thirteen CLB inputs and four CLB outputs provide access to the function generators and storage elements. These inputs and outputs connect to the programmable interconnect resources outside the block.

Function Generators

Four independent inputs are provided to each of two function generators (F1 - F4 and G1 - G4). These function generators, with outputs labeled F’ and G’, are each capable of implementing any arbitrarily defined Boolean function of four inputs. The function generators are implemented as memory look-up tables. The propagation delay is therefore independent of the function implemented.

A third function generator, labeled H’, can implement any Boolean function of its three inputs. Two of these inputs can optionally be the F’ and G’ functional generator outputs. Alternatively, one or both of these inputs can come from outside the CLB (H2, H0). The third input must come from outside the block (H1).

Signals from the function generators can exit the CLB on two outputs. F’ or H’ can be connected to the X output. G’ or H’ can be connected to the Y output.

A CLB can be used to implement any of the following functions:

- any function of up to four variables, plus any second function of up to four unrelated variables, plus any third function of up to three unrelated variables
- any single function of five variables
- any function of four variables together with some functions of six variables
- some functions of up to nine variables.

Implementing wide functions in a single block reduces both the number of blocks required and the delay in the signal path, achieving both increased capacity and speed.

The versatility of the CLB function generators significantly improves system speed. In addition, the design-software tools can deal with each function generator independently. This flexibility improves cell usage.

---

1. When three separate functions are generated, one of the function outputs must be captured in a flip-flop internal to the CLB. Only two unregistered function generator outputs are available from the CLB.
Flip-Flops

The CLB can pass the combinatorial output(s) to the interconnect network, but can also store the combinatorial results or other incoming data in one or two flip-flops, and connect their outputs to the interconnect network as well.

The two edge-triggered D-type flip-flops have common clock (K) and clock enable (EC) inputs. Either or both clock inputs can also be permanently enabled. Storage element functionality is described in Table 3.

Latches (XC4000X only)

The CLB storage elements can also be configured as latches. The two latches have common clock (K) and clock enable (EC) inputs. Storage element functionality is described in Table 3.

Clock Input

Each flip-flop can be triggered on either the rising or falling clock edge. The clock pin is shared by both storage elements. However, the clock is individually invertible for each storage element. Any inverter placed on the clock input is automatically absorbed into the CLB.

Clock Enable

The clock enable signal (EC) is active High. The EC pin is shared by both storage elements. If left unconnected for either, the clock enable for that storage element defaults to the active state. EC is not invertible within the CLB.

Table 3: CLB Storage Element Functionality (active rising edge is shown)

<table>
<thead>
<tr>
<th>Mode</th>
<th>K</th>
<th>EC</th>
<th>SR</th>
<th>D</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-Up or</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>SR</td>
</tr>
<tr>
<td>GSR</td>
<td>X</td>
<td>X</td>
<td>1</td>
<td>X</td>
<td>SR</td>
</tr>
<tr>
<td>Flip-Flop</td>
<td>X</td>
<td>X</td>
<td>1*</td>
<td>0*</td>
<td>D</td>
</tr>
<tr>
<td>Latch</td>
<td>0</td>
<td>X</td>
<td>0*</td>
<td>X</td>
<td>Q</td>
</tr>
<tr>
<td>Both</td>
<td>0</td>
<td>1*</td>
<td>0*</td>
<td>D</td>
<td>Q</td>
</tr>
</tbody>
</table>

Legend:
- Don’t care
- Rising edge
- SR Set or Reset value. Reset is default.
- 0* Input is Low or unconnected (default value)
- 1* Input is High or unconnected (default value)
Set/Reset
An asynchronous storage element input (SR) can be configured as either set or reset. This configuration option determines the state in which each flip-flop becomes operational after configuration. It also determines the effect of a Global Set/Reset pulse during normal operation, and the effect of a pulse on the SR pin of the CLB. All three set/reset functions for any single flip-flop are controlled by the same configuration data bit.

The set/reset state can be independently specified for each flip-flop. This input can also be independently disabled for either flip-flop.

The set/reset state is specified by using the INIT attribute, or by placing the appropriate set or reset flip-flop library symbol.

SR is active High. It is not invertible within the CLB.

Global Set/Reset
A separate Global Set/Reset line (not shown in Figure 2) sets or clears each storage element during power-up, reconfiguration, or when a dedicated Reset net is driven active. This global net (GSR) does not compete with other routing resources; it uses a dedicated distribution network.

Each flip-flop is configured as either globally set or reset in the same way that the local set/reset (SR) is specified. Therefore, if a flip-flop is set by SR, it is also set by GSR. Similarly, a reset flip-flop is reset by both SR and GSR.

Two fast feed-through paths are available, as shown in Figure 2. A two-to-one multiplexer on each of the XQ and YQ outputs selects between a storage element output and any of the control inputs. This bypass is sometimes used by the automated router to repower internal signals.

Control Signals
Multiplexers in the CLB map the four control inputs (C1 - C4 in Figure 2) into the four internal control signals (H1, DIN/H2, SR/H0, and EC). Any of these inputs can drive any of the four internal control signals.

When the logic function is enabled, the four inputs are:
- EC — Enable Clock
- SR/H0 — Asynchronous Set/Reset or H function generator Input 0
- DIN/H2 — Direct In or H function generator Input 2
- H1 — H function generator Input 1.

When the memory function is enabled, the four inputs are:
- EC — Enable Clock
- WE — Write Enable
- D0 — Data Input to F and/or G function generator
- D1 — Data input to G function generator (16x1 and 16x2 modes) or 5th Address bit (32x1 mode).

Using FPGA Flip-Flops and Latches
The abundance of flip-flops in the XC4000 Series invites pipelined designs. This is a powerful way of increasing performance by breaking the function into smaller subfunctions and executing them in parallel, passing on the results through pipeline flip-flops. This method should be seriously considered wherever throughput is more important than latency.

To include a CLB flip-flop, place the appropriate library symbol. For example, FDCE is a D-type flip-flop with clock enable and asynchronous clear. The corresponding latch symbol (for the XC4000X only) is called LDCE.

In XC4000 Series devices, the flip flops can be used as registers or shift registers without blocking the function generators from performing a different, perhaps unrelated task. This ability increases the functional capacity of the devices.

The CLB setup time is specified between the function generator inputs and the clock input K. Therefore, the specified CLB flip-flop setup time includes the delay through the function generator.

Using Function Generators as RAM
Optional modes for each CLB make the memory look-up tables in the F’ and G’ function generators usable as an array of Read/Write memory cells. Available modes are level-sensitive (similar to the XC4000/A/H families), edge-triggered, and dual-port edge-triggered. Depending on the selected mode, a single CLB can be configured as either a 16x2, 32x1, or 16x1 bit array.

Data Inputs and Outputs
The source of a storage element data input is programmable. It is driven by any of the functions F’, G’, and H’, or by the Direct In (DIN) block input. The flip-flops or latches drive the XQ and YQ CLB outputs.
Supported CLB memory configurations and timing modes for single- and dual-port modes are shown in Table 4.

XC4000 Series devices are the first programmable logic devices with edge-triggered (synchronous) and dual-port RAM accessible to the user. Edge-triggered RAM simplifies system timing. Dual-port RAM doubles the effective throughput of FIFO applications. These features can be individually programmed in any XC4000 Series CLB.

**Advantages of On-Chip and Edge-Triggered RAM**

The on-chip RAM is extremely fast. The read access time is the same as the logic delay. The write access time is slightly slower. Both access times are much faster than any off-chip solution, because they avoid I/O delays.

Edge-triggered RAM, also called synchronous RAM, is a feature never before available in a Field Programmable Gate Array. The simplicity of designing with edge-triggered RAM, and the markedly higher achievable performance, add up to a significant improvement over existing devices with on-chip RAM.

Three application notes are available from Xilinx that discuss edge-triggered RAM: “XC4000E Edge-Triggered and Dual-Port RAM Capability,” “Implementing FIFOs in XC4000E RAM,” and “Synchronous and Asynchronous FIFO Designs.” All three application notes apply to both XC4000E and XC4000X RAM.

**Table 4: Supported RAM Modes**

<table>
<thead>
<tr>
<th></th>
<th>16 x 1</th>
<th>16 x 2</th>
<th>32 x 1</th>
<th>Edge-Triggered Timing</th>
<th>Level-Sensitive Timing</th>
</tr>
</thead>
<tbody>
<tr>
<td>Single-Port</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>Dual-Port</td>
<td>√</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**RAM Configuration Options**

The function generators in any CLB can be configured as RAM arrays in the following sizes:

- Two 16x1 RAMs: two data inputs and two data outputs with identical or, if preferred, different addressing for each RAM
- One 32x1 RAM: one data input and one data output.

One F or G function generator can be configured as a 16x1 RAM while the other function generators are used to implement any function of up to 5 inputs.

Additionally, the XC4000 Series RAM may have either of two timing modes:

- Edge-Triggered (Synchronous): data written by the designated edge of the CLB clock. WE acts as a true clock enable.
- Level-Sensitive (Asynchronous): an external WE signal acts as the write strobe.

The selected timing mode applies to both function generators within a CLB when both are configured as RAM.

The number of read ports is also programmable:

- Single Port: each function generator has a common read and write port
- Dual Port: both function generators are configured together as a single 16x1 dual-port RAM with one write port and two read ports. Simultaneous read and write operations to the same or different addresses are supported.

RAM configuration options are selected by placing the appropriate library symbol.

**Choosing a RAM Configuration Mode**

The appropriate choice of RAM mode for a given design should be based on timing and resource requirements, desired functionality, and the simplicity of the design process. Recommended usage is shown in Table 5.

The difference between level-sensitive, edge-triggered, and dual-port RAM is only in the write operation. Read operation and timing is identical for all modes of operation.

**Table 5: RAM Mode Selection**

<table>
<thead>
<tr>
<th></th>
<th>Level-Sensitive</th>
<th>Edge-Triggered</th>
<th>Dual-Port Edge-Triggered</th>
</tr>
</thead>
<tbody>
<tr>
<td>Use for New Designs?</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Size (16x1, Registered)</td>
<td>1/2 CLB</td>
<td>1/2 CLB</td>
<td>1 CLB</td>
</tr>
<tr>
<td>Simultaneous Read/Write</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>Relative Performance</td>
<td>X</td>
<td>2X</td>
<td>2X (4X effective)</td>
</tr>
</tbody>
</table>

**RAM Inputs and Outputs**

The F1-F4 and G1-G4 inputs to the function generators act as address lines, selecting a particular memory cell in each look-up table.

The functionality of the CLB control signals changes when the function generators are configured as RAM. The DIN/H2, H1, and SR/H0 lines become the two data inputs (D0, D1) and the Write Enable (WE) input for the 16x2 memory. When the 32x1 configuration is selected, D1 acts as the fifth address bit and D0 is the data input.

The contents of the memory cell(s) being addressed are available at the F’ and G’ function-generator outputs. They can exit the CLB through its X and Y outputs, or can be captured in the CLB flip-flop(s).

Configuring the CLB function generators as Read/Write memory does not affect the functionality of the other por-
tions of the CLB, with the exception of the redefinition of the control signals. In 16x2 and 16x1 modes, the H’ function generator can be used to implement Boolean functions of F’, G’, and D1, and the D flip-flops can latch the F’, G’, H’, or D0 signals.

**Single-Port Edge-Triggered Mode**

Edge-triggered (synchronous) RAM simplifies timing requirements. XC4000 Series edge-triggered RAM timing operates like writing to a data register. Data and address are presented. The register is enabled for writing by a logic High on the write enable input, WE. Then a rising or falling clock edge loads the data into the register, as shown in Figure 4.

The Write Clock input (WCLK) can be configured as active on either the rising edge (default) or the falling edge. It uses the same CLB pin (K) used to clock the CLB flip-flops, but it can be independently inverted. Consequently, the RAM output can optionally be registered within the same CLB either by the same clock edge as the RAM, or by the opposite edge of this clock. The sense of WCLK applies to both function generators in the CLB when both are configured as RAM.

The WE pin is active-High and is not invertible within the CLB.

**Note:** The pulse following the active edge of WCLK (T_{WPS} in Figure 4) must be less than one millisecond wide. For most applications, this requirement is not overly restrictive; however, it must not be forgotten. Stopping WCLK at this point in the write cycle could result in excessive current and even damage to the larger devices if many CLBs are configured as edge-triggered RAM.

**Table 6: Single-Port Edge-Triggered RAM Signals**

<table>
<thead>
<tr>
<th>RAM Signal</th>
<th>CLB Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>D0 or D1 (16x2, 16x1), D0 (32x1)</td>
<td>Data In</td>
</tr>
<tr>
<td>A[3:0]</td>
<td>F1-F4 or G1-G4</td>
<td>Address</td>
</tr>
<tr>
<td>WE</td>
<td>WE</td>
<td>Write Enable</td>
</tr>
<tr>
<td>WCLK</td>
<td>K</td>
<td>Clock</td>
</tr>
<tr>
<td>SPO (Data Out)</td>
<td>F' or G'</td>
<td>Single Port Out (Data Out)</td>
</tr>
</tbody>
</table>

**Figure 4: Edge-Triggered RAM Write Timing**

Complex timing relationships between address, data, and write enable signals are not required, and the external write enable pulse becomes a simple clock enable. The active edge of WCLK latches the address, input data, and WE signals. An internal write pulse is generated that performs the write. See Figure 5 and Figure 6 for block diagrams of a CLB configured as 16x2 and 32x1 edge-triggered, single-port RAM.

The relationships between CLB pins and RAM inputs and outputs for single-port, edge-triggered mode are shown in Table 6.
Figure 5: 16x2 (or 16x1) Edge-Triggered Single-Port RAM

Figure 6: 32x1 Edge-Triggered Single-Port RAM (F and G addresses are identical)
Dual-Port Edge-Triggered Mode

In dual-port mode, both the F and G function generators are used to create a single 16x1 RAM array with one write port and two read ports. The resulting RAM array can be read and written simultaneously at two independent addresses. Simultaneous read and write operations at the same address are also supported.

Dual-port mode always has edge-triggered write timing, as shown in Figure 4.

Figure 7 shows a simple model of an XC4000 Series CLB configured as dual-port RAM. One address port, labeled A[3:0], supplies both the read and write address for the F function generator. This function generator behaves the same as a 16x1 single-port edge-triggered RAM array. The RAM output, Single Port Out (SPO), appears at the F function generator output. SPO, therefore, reflects the data at address A[3:0].

The other address port, labeled DPRA[3:0] for Dual Port Read Address, supplies the read address for the G function generator. The write address for the G function generator, however, comes from the address A[3:0]. The output from this 16x1 RAM array, Dual Port Out (DPO), appears at the G function generator output. DPO, therefore, reflects the data at address DPRA[3:0].

Therefore, by using A[3:0] for the write address and DPRA[3:0] for the read address, and reading only the DPO output, a FIFO that can read and write simultaneously is easily generated. Simultaneous access doubles the effective throughput of the FIFO.

The relationships between CLB pins and RAM inputs and outputs for dual-port, edge-triggered mode are shown in Table 7. See Figure 8 on page 4-16 for a block diagram of a CLB configured in this mode.

### Table 7: Dual-Port Edge-Triggered RAM Signals

<table>
<thead>
<tr>
<th>RAM Signal</th>
<th>CLB Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>D0</td>
<td>Data In</td>
</tr>
<tr>
<td>A[3:0]</td>
<td>F1-F4</td>
<td>Read Address for F, Write Address for F and G</td>
</tr>
<tr>
<td>DPRA[3:0]</td>
<td>G1-G4</td>
<td>Read Address for G</td>
</tr>
<tr>
<td>WE</td>
<td>WE</td>
<td>Write Enable</td>
</tr>
<tr>
<td>WCLK</td>
<td>K</td>
<td>Clock</td>
</tr>
<tr>
<td>SPO</td>
<td>F</td>
<td>Single Port Out (addressed by A[3:0])</td>
</tr>
<tr>
<td>DPO</td>
<td>G</td>
<td>Dual Port Out (addressed by DPRA[3:0])</td>
</tr>
</tbody>
</table>

**Note:** The pulse following the active edge of WCLK (T_WPS in Figure 4) must be less than one millisecond wide. For most applications, this requirement is not overly restrictive; however, it must not be forgotten. Stopping WCLK at this point in the write cycle could result in excessive current and even damage to the larger devices if many CLBs are configured as edge-triggered RAM.

Single-Port Level-Sensitive Timing Mode

**Note:** Edge-triggered mode is recommended for all new designs. Level-sensitive mode, also called asynchronous mode, is still supported for XC4000 Series backward-compatibility with the XC4000 family.

Level-sensitive RAM timing is simple in concept but can be complicated in execution. Data and address signals are presented, then a positive pulse on the write enable pin (WE) performs a write into the RAM at the designated address. As indicated by the “level-sensitive” label, this RAM acts like a latch. During the WE High pulse, changing the data lines results in new data written to the old address. Changing the address lines while WE is High results in spurious data written to the new address—and possibly at other addresses as well, as the address lines inevitably do not all change simultaneously.

The user must generate a carefully timed WE signal. The delay on the WE signal and the address lines must be carefully verified to ensure that WE does not become active until after the address lines have settled, and that WE goes inactive before the address lines change again. The data must be stable before and after the falling edge of WE.

In practical terms, WE is usually generated by a 2X clock. If a 2X clock is not available, the falling edge of the system clock can be used. However, there are inherent risks in this approach, since the WE pulse must be guaranteed inactive before the next rising edge of the system clock. Several older application notes are available from Xilinx that discuss the design of level-sensitive RAMs. These application notes include XAPP031, “Using the XC4000 RAM Capability,” and XAPP042, “High-Speed RAM Design in XC4000.” However, the edge-triggered RAM available in the XC4000 Series is superior to level-sensitive RAM for almost every application.

---

Dual-Port Edge-Triggered Mode

In dual-port mode, both the F and G function generators are used to create a single 16x1 RAM array with one write port and two read ports. The resulting RAM array can be read and written simultaneously at two independent addresses. Simultaneous read and write operations at the same address are also supported.

Dual-port mode always has edge-triggered write timing, as shown in Figure 4.

Figure 7 shows a simple model of an XC4000 Series CLB configured as dual-port RAM. One address port, labeled A[3:0], supplies both the read and write address for the F function generator. This function generator behaves the same as a 16x1 single-port edge-triggered RAM array. The RAM output, Single Port Out (SPO), appears at the F function generator output. SPO, therefore, reflects the data at address A[3:0].

The other address port, labeled DPRA[3:0] for Dual Port Read Address, supplies the read address for the G function generator. The write address for the G function generator, however, comes from the address A[3:0]. The output from this 16x1 RAM array, Dual Port Out (DPO), appears at the G function generator output. DPO, therefore, reflects the data at address DPRA[3:0].

Therefore, by using A[3:0] for the write address and DPRA[3:0] for the read address, and reading only the DPO output, a FIFO that can read and write simultaneously is easily generated. Simultaneous access doubles the effective throughput of the FIFO.

The relationships between CLB pins and RAM inputs and outputs for dual-port, edge-triggered mode are shown in Table 7. See Figure 8 on page 4-16 for a block diagram of a CLB configured in this mode.

### Table 7: Dual-Port Edge-Triggered RAM Signals

<table>
<thead>
<tr>
<th>RAM Signal</th>
<th>CLB Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>D0</td>
<td>Data In</td>
</tr>
<tr>
<td>A[3:0]</td>
<td>F1-F4</td>
<td>Read Address for F, Write Address for F and G</td>
</tr>
<tr>
<td>DPRA[3:0]</td>
<td>G1-G4</td>
<td>Read Address for G</td>
</tr>
<tr>
<td>WE</td>
<td>WE</td>
<td>Write Enable</td>
</tr>
<tr>
<td>WCLK</td>
<td>K</td>
<td>Clock</td>
</tr>
<tr>
<td>SPO</td>
<td>F</td>
<td>Single Port Out (addressed by A[3:0])</td>
</tr>
<tr>
<td>DPO</td>
<td>G</td>
<td>Dual Port Out (addressed by DPRA[3:0])</td>
</tr>
</tbody>
</table>

**Note:** The pulse following the active edge of WCLK (T_WPS in Figure 4) must be less than one millisecond wide. For most applications, this requirement is not overly restrictive; however, it must not be forgotten. Stopping WCLK at this point in the write cycle could result in excessive current and even damage to the larger devices if many CLBs are configured as edge-triggered RAM.

Single-Port Level-Sensitive Timing Mode

**Note:** Edge-triggered mode is recommended for all new designs. Level-sensitive mode, also called asynchronous mode, is still supported for XC4000 Series backward-compatibility with the XC4000 family.

Level-sensitive RAM timing is simple in concept but can be complicated in execution. Data and address signals are presented, then a positive pulse on the write enable pin (WE) performs a write into the RAM at the designated address. As indicated by the “level-sensitive” label, this RAM acts like a latch. During the WE High pulse, changing the data lines results in new data written to the old address. Changing the address lines while WE is High results in spurious data written to the new address—and possibly at other addresses as well, as the address lines inevitably do not all change simultaneously.

The user must generate a carefully timed WE signal. The delay on the WE signal and the address lines must be carefully verified to ensure that WE does not become active until after the address lines have settled, and that WE goes inactive before the address lines change again. The data must be stable before and after the falling edge of WE.

In practical terms, WE is usually generated by a 2X clock. If a 2X clock is not available, the falling edge of the system clock can be used. However, there are inherent risks in this approach, since the WE pulse must be guaranteed inactive before the next rising edge of the system clock. Several older application notes are available from Xilinx that discuss the design of level-sensitive RAMs. These application notes include XAPP031, “Using the XC4000 RAM Capability,” and XAPP042, “High-Speed RAM Design in XC4000.” However, the edge-triggered RAM available in the XC4000 Series is superior to level-sensitive RAM for almost every application.
Figure 9 shows the write timing for level-sensitive, single-port RAM.

The relationships between CLB pins and RAM inputs and outputs for single-port level-sensitive mode are shown in Table 8.

Figure 10 and Figure 11 show block diagrams of a CLB configured as 16x2 and 32x1 level-sensitive, single-port RAM.

Initializing RAM at Configuration

Both RAM and ROM implementations of the XC4000 Series devices are initialized during configuration. The initial contents are defined via an INIT attribute or property attached to the RAM or ROM symbol, as described in the schematic library guide. If not defined, all RAM contents are initialized to all zeros, by default.

RAM initialization occurs only during configuration. The RAM content is not affected by Global Set/Reset.

Table 8: Single-Port Level-Sensitive RAM Signals

<table>
<thead>
<tr>
<th>RAM Signal</th>
<th>CLB Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>D0 or D1</td>
<td>Data In</td>
</tr>
<tr>
<td>A[3:0]</td>
<td>F1-F4 or G1-G4</td>
<td>Address</td>
</tr>
<tr>
<td>WE</td>
<td>WE</td>
<td>Write Enable</td>
</tr>
<tr>
<td>O</td>
<td>F' or G'</td>
<td>Data Out</td>
</tr>
</tbody>
</table>
Figure 9: Level-Sensitive RAM Write Timing

Figure 10: 16x2 (or 16x1) Level-Sensitive Single-Port RAM
Fast Carry Logic

Each CLB F and G function generator contains dedicated arithmetic logic for the fast generation of carry and borrow signals. This extra output is passed on to the function generator in the adjacent CLB. The carry chain is independent of normal routing resources.

Dedicated fast carry logic greatly increases the efficiency and performance of adders, subtractors, accumulators, comparators and counters. It also opens the door to many new applications involving arithmetic operation, where the previous generations of FPGAs were not fast enough or too inefficient. High-speed address offset calculations in microprocessor or graphics systems, and high-speed addition in digital signal processing are two typical applications.

The two 4-input function generators can be configured as a 2-bit adder with built-in hidden carry that can be expanded to any length. This dedicated carry circuitry is so fast and efficient that conventional speed-up methods like carry generate/propagate are meaningless even at the 16-bit level, and of marginal benefit at the 32-bit level.

This fast carry logic is one of the more significant features of the XC4000 Series, speeding up arithmetic and counting into the 70 MHz range.

The carry chain in XC4000E devices can run either up or down. At the top and bottom of the columns where there are no CLBs above and below, the carry is propagated to the right. (See Figure 12.) In order to improve speed in the high-capacity XC4000X devices, which can potentially have very long carry chains, the carry chain travels upward only, as shown in Figure 13. Additionally, standard interconnect can be used to route a carry signal in the downward direction.

Figure 14 on page 4-20 shows an XC4000E CLB with dedicated fast carry logic. The carry logic in the XC4000X is similar, except that COUT exits at the top only, and the signal CINDOWN does not exist. As shown in Figure 14, the carry logic shares operand and control inputs with the function generators. The carry outputs connect to the function generators, where they are combined with the operands to form the sums.

Figure 15 on page 4-21 shows the details of the carry logic for the XC4000E. This diagram shows the contents of the box labeled "CARRY LOGIC" in Figure 14. The XC4000X carry logic is very similar, but a multiplexer on the pass-through carry chain has been eliminated to reduce delay. Additionally, in the XC4000X the multiplexer on the G4 path has a memory-programmable 0 input, which permits G4 to...

---

Figure 11: 32x1 Level-Sensitive Single-Port RAM (F and G addresses are identical)
directly connect to COUT. G4 thus becomes an additional high-speed initialization path for carry-in.

The dedicated carry logic is discussed in detail in Xilinx document XAPP 013: “Using the Dedicated Carry Logic in XC4000.” This discussion also applies to XC4000E devices, and to XC4000X devices when the minor logic changes are taken into account.

The fast carry logic can be accessed by placing special library symbols, or by using Xilinx Relationally Placed Macros (RPMs) that already include these symbols.

Figure 12: Available XC4000E Carry Propagation Paths

Figure 13: Available XC4000X Carry Propagation Paths (dotted lines use general interconnect)
Figure 14: Fast Carry Logic in XC4000E CLB (shaded area not present in XC4000X)
Input/Output Blocks (IOBs)

User-configurable input/output blocks (IOBs) provide the interface between external package pins and the internal logic. Each IOB controls one package pin and can be configured for input, output, or bidirectional signals.

Figure 16 shows a simplified block diagram of the XC4000E IOB. A more complete diagram which includes the boundary scan logic of the XC4000E IOB can be found in Figure 41 on page 4-44, in the “Boundary Scan” section.

The XC4000X IOB contains some special features not included in the XC4000E IOB. These features are highlighted in a simplified block diagram found in Figure 17, and discussed throughout this section. When XC4000X special features are discussed, they are clearly identified in the text. Any feature not so identified is present in both XC4000E and XC4000X devices.

IOB Input Signals

Two paths, labeled I1 and I2 in Figure 16 and Figure 17, bring input signals into the array. Inputs also connect to an input register that can be programmed as either an edge-triggered flip-flop or a level-sensitive latch.

The choice is made by placing the appropriate library symbol. For example, IFD is the basic input flip-flop (rising edge triggered), and ILD is the basic input latch (transparent-High). Variations with inverted clocks are available, and some combinations of latches and flip-flops can be implemented in a single IOB, as described in the XACT Libraries Guide.

The XC4000E inputs can be globally configured for either TTL (1.2V) or 5.0 volt CMOS thresholds, using an option in the bitstream generation software. There is a slight input hysteresis of about 300mV. The XC4000E output levels are also configurable; the two global adjustments of input threshold and output level are independent.

Inputs on the XC4000XL are TTL compatible and 3.3V CMOS compatible. Outputs on the XC4000XL are pulled to the 3.3V positive supply.

The inputs of XC4000 Series 5-Volt devices can be driven by the outputs of any 3.3-Volt device, if the 5-Volt inputs are in TTL mode.

Supported sources for XC4000 Series device inputs are shown in Table 9.
Figure 16: Simplified Block Diagram of XC4000E IOB

Figure 17: Simplified Block Diagram of XC4000X IOB (shaded areas indicate differences from XC4000E)
XC4000XL 5-Volt Tolerant I/Os

The I/Os on the XC4000XL are fully 5-volt tolerant even though the VCC is 3.3 volts. This allows 5 V signals to directly connect to the XC4000XL inputs without damage, as shown in Table 9. In addition, the 3.3 volt VCC can be applied before or after 5 volt signals are applied to the I/Os. This makes the XC4000XL immune to power supply sequencing problems.

Registered Inputs

The I1 and I2 signals that exit the block can each carry either the direct or registered input signal.

The input and output storage elements in each IOB have a common clock enable input, which, through configuration, can be activated individually for the input or output flip-flop, or both. This clock enable operates exactly like the EC pin on the XC4000 Series CLB. It cannot be inverted within the IOB.

The storage element behavior is shown in Table 10.

Table 10: Input Register Functionality (active rising edge is shown)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Clock</th>
<th>Clock Enable</th>
<th>D</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-Up or GSR</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>SR</td>
</tr>
<tr>
<td>Flip-Flop</td>
<td>_/</td>
<td>1*</td>
<td>D</td>
<td>D</td>
</tr>
<tr>
<td></td>
<td>0</td>
<td>X</td>
<td>X</td>
<td>Q</td>
</tr>
<tr>
<td>Latch</td>
<td>1</td>
<td>1*</td>
<td>X</td>
<td>Q</td>
</tr>
<tr>
<td></td>
<td>0</td>
<td>1*</td>
<td>D</td>
<td>D</td>
</tr>
<tr>
<td>Both</td>
<td>X</td>
<td>0</td>
<td>X</td>
<td>Q</td>
</tr>
</tbody>
</table>

Legend:
- X: Don’t care
- _/: Rising edge
- SR: Set or Reset value. Reset is default.
- 0*: Input is Low or unconnected (default value)
- 1*: Input is High or unconnected (default value)

Optional Delay Guarantees Zero Hold Time

The data input to the register can optionally be delayed by several nanoseconds. With the delay enabled, the setup time of the input flip-flop is increased so that normal clock routing does not result in a positive hold-time requirement. A positive hold time requirement can lead to unreliable, temperature- or processing-dependent operation.

The input flip-flop setup time is defined between the data measured at the device I/O pin and the clock input at the IOB (not at the clock pin). Any routing delay from the device clock pin to the clock input of the IOB must, therefore, be subtracted from this setup time to arrive at the real setup time requirement relative to the device pins. A short specified setup time might, therefore, result in a negative setup time at the device pins, i.e., a positive hold-time requirement.

When a delay is inserted on the data line, more clock delay can be tolerated without causing a positive hold-time requirement. Sufficient delay eliminates the possibility of a data hold-time requirement at the external pin. The maximum delay is therefore inserted as the default.

The XC4000E IOB has a one-tap delay element: either the delay is inserted (default), or it is not. The delay guarantees a zero hold time with respect to clocks routed through any of the XC4000E global clock buffers. (See “Global Nets and Buffers (XC4000E only)” on page 4-36 for a description of the global clock buffers in the XC4000E.) For a shorter input register setup time, with non-zero hold, attach a NODELAY attribute or property to the flip-flop.

The XC4000X IOB has a two-tap delay element, with choices of a full delay, a partial delay, or no delay. The attributes or properties used to select the desired delay are shown in Table 11. The choices are no added attribute, MEDDELAY, and NODELAY. The default setting, with no added attribute, ensures no hold time with respect to any of the XC4000X clock buffers, including the Global Low-Skew buffers. MEDDELAY ensures no hold time with respect to the Global Early buffers. Inputs with NODELAY may have a positive hold time with respect to all clock buffers. For a description of each of these buffers, see “Global Nets and Buffers (XC4000X only)” on page 4-38.

Table 11: XC4000X IOB Input Delay Element

<table>
<thead>
<tr>
<th>Value</th>
<th>When to Use</th>
</tr>
</thead>
<tbody>
<tr>
<td>full delay (default, no attribute added)</td>
<td>Zero Hold with respect to Global Low-Skew Buffer, Global Early Buffer</td>
</tr>
<tr>
<td>MEDDELAY</td>
<td>Zero Hold with respect to Global Early Buffer</td>
</tr>
<tr>
<td>NODELAY</td>
<td>Short Setup, positive Hold time</td>
</tr>
</tbody>
</table>
Additional Input Latch for Fast Capture (XC4000X only)

The XC4000X IOB has an additional optional latch on the input. This latch, as shown in Figure 17, is clocked by the output clock — the clock used for the output flip-flop — rather than the input clock. Therefore, two different clocks can be used to clock the two input storage elements. This additional latch allows the very fast capture of input data, which is then synchronized to the internal clock by the IOB flip-flop or latch.

To use this Fast Capture technique, drive the output clock pin (the Fast Capture latching signal) from the output of one of the Global Early buffers supplied in the XC4000X. The second storage element should be clocked by a Global Low-Skew buffer, to synchronize the incoming data to the internal logic. (See Figure 18.) These special buffers are described in “Global Nets and Buffers (XC4000X only)” on page 4-38.

The Fast Capture latch (FCL) is designed primarily for use with a Global Early buffer. For Fast Capture, a single clock signal is routed through both a Global Early buffer and a Global Low-Skew buffer. (The two buffers share an input pad.) The Fast Capture latch is clocked by the Global Early buffer, and the standard IOB flip-flop or latch is clocked by the Global Low-Skew buffer. This mode is the safest way to use the Fast Capture latch, because the clock buffers on both storage elements are driven by the same pad. There is no external skew between clock pads to create potential problems.

To place the Fast Capture latch in a design, use one of the special library symbols, ILFFX or ILFLX. ILFFX is a transparent-Low Fast Capture latch followed by an active-High input flip-flop. ILFLX is a transparent-Low Fast Capture latch followed by a transparent-High input latch. Any of the clock inputs can be inverted before driving the library element, and the inverter is absorbed into the IOB. If a single BUFG output is used to drive both clock inputs, the software automatically runs the clock through both a Global Low-Skew buffer and a Global Early buffer, and clocks the Fast Capture latch appropriately.

Figure 17 on page 4-22 also shows a two-tap delay on the input. By default, if the Fast Capture latch is used, the Xilinx software assumes a Global Early buffer is driving the clock, and selects MEDDELAY to ensure a zero hold time. Select the desired delay based on the discussion in the previous subsection.

**IOB Output Signals**

Output signals can be optionally inverted within the IOB, and can pass directly to the pad or be stored in an edge-triggered flip-flop. The functionality of this flip-flop is shown in Table 12.

An active-High 3-state signal can be used to place the output buffer in a high-impedance state, implementing 3-state outputs or bidirectional I/O. Under configuration control, the output (OUT) and output 3-state (T) signals can be inverted. The polarity of these signals is independently configured for each IOB.

The 4-mA maximum output current specification of many FPGAs often forces the user to add external buffers, which are especially cumbersome on bidirectional I/O lines. The XC4000E and XC4000EX/XL devices solve many of these problems by providing a guaranteed output sink current of 12 mA. Two adjacent outputs can be interconnected externally to sink up to 24 mA. The XC4000E and XC4000EX/XL FPGAs can thus directly drive buses on a printed circuit board.

By default, the output pull-up structure is configured as a TTL-like totem-pole. The High driver is an n-channel pull-up transistor, pulling to a voltage one transistor threshold below Vcc. Alternatively, the outputs can be globally configured as CMOS drivers, with p-channel pull-up transistors pulling to Vcc. This option, applied using the bitstream generation software, applies to all outputs on the device. It is not individually programmable. In the XC4000XL, all outputs are pulled to the positive supply rail.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Clock</th>
<th>Clock Enable</th>
<th>T</th>
<th>D</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-Up</td>
<td>X</td>
<td>X</td>
<td>0*</td>
<td>X</td>
<td>SR</td>
</tr>
<tr>
<td>or GSR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Flip-Flop</td>
<td>X</td>
<td>0*</td>
<td>X</td>
<td>Q</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1*</td>
<td>0*</td>
<td>D</td>
<td>D</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0</td>
<td>X</td>
<td>0*</td>
<td>X</td>
<td>Q</td>
</tr>
</tbody>
</table>

**Legend:**
- X Don't care
- Rising edge
- SR Set or Reset value. Reset is default.
- 0*/1* Input is Low or unconnected (default value)
- Z Input is High or unconnected (default value)
- 3-state

Figure 18: Examples Using XC4000X FCL
Any XC4000 Series 5-Volt device with its outputs configured in TTL mode can drive the inputs of any typical 3.3-Volt device. (For a detailed discussion of how to interface between 5 V and 3.3 V devices, see the 3V Products section of The Programmable Logic Data Book.)

Supported destinations for XC4000 Series device outputs are shown in Table 13.

An output can be configured as open-drain (open-collector) by placing an OBUFT symbol in a schematic or HDL code, then tying the 3-state pin (T) to the output signal, and the input pin (I) to Ground. (See Figure 19.)

### Table 13: Supported Destinations for XC4000 Series Outputs

<table>
<thead>
<tr>
<th>Destination</th>
<th>3.3 V, CMOS</th>
<th>5 V, TTL</th>
<th>5 V, CMOS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Any typical device, Vcc = 3.3 V, CMOS-threshold inputs</td>
<td>√</td>
<td>√</td>
<td>some ²</td>
</tr>
<tr>
<td>Any device, Vcc = 5 V, TTL-threshold inputs</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>Any device, Vcc = 5 V, CMOS-threshold inputs</td>
<td>Unreliable Data</td>
<td>√</td>
<td></td>
</tr>
</tbody>
</table>

1. Only if destination device has 5-V tolerant inputs

![Figure 19: Open-Drain Output](image)

### Output Slew Rate

The slew rate of each output buffer is, by default, reduced, to minimize power bus transients when switching non-critical signals. For critical signals, attach a FAST attribute or property to the output buffer or flip-flop.

For XC4000E devices, maximum total capacitive load for simultaneous fast mode switching in the same direction is 200 pF for all package pins between each Power/Ground pin pair. For XC4000X devices, additional internal Power/Ground pin pairs are connected to special Power and Ground planes within the packages, to reduce ground bounce. Therefore, the maximum total capacitive load is 300 pF between each external Power/Ground pin pair. Maximum loading may vary for the low-voltage devices.

For slew-rate limited outputs this total is two times larger for each device type: 400 pF for XC4000E devices and 600 pF for XC4000X devices. This maximum capacitive load should not be exceeded, as it can result in ground bounce of greater than 1.5 V amplitude and more than 5 ns duration. This level of ground bounce may cause undesired transient behavior on an output, or in the internal logic. This restriction is common to all high-speed digital ICs, and is not particular to Xilinx or the XC4000 Series.

XC4000 Series devices have a feature called “Soft Start-up,” designed to reduce ground bounce when all outputs are turned on simultaneously at the end of configuration. When the configuration process is finished and the device starts up, the first activation of the outputs is automatically slew-rate limited. Immediately following the initial activation of the I/O, the slew rate of the individual outputs is determined by the individual configuration option for each IOB.

### Global Three-State

A separate Global 3-State line (not shown in Figure 16 or Figure 17) forces all FPGA outputs to the high-impedance state, unless boundary scan is enabled and is executing an EXTEST instruction. This global net (GTS) does not compete with other routing resources; it uses a dedicated distribution network.

GTS can be driven from any user-programmable pin as a global 3-state input. To use this global net, place an input pad and input buffer in the schematic or HDL code, driving the GTS pin of the STARTUP symbol. A specific pin location can be assigned to this input using a LOC attribute or property, just as with any other user-programmable pad. An inverter can optionally be inserted after the input buffer to invert the sense of the Global 3-State signal. Using GTS is similar to GSR. See Figure 3 on page 4-11 for details.

Alternatively, GTS can be driven from any internal node.
Output Multiplexer/2-Input Function Generator (XC4000X only)

As shown in Figure 17 on page 4-22, the output path in the XC4000X IOB contains an additional multiplexer not available in the XC4000E IOB. The multiplexer can also be configured as a 2-input function generator, implementing a pass-gate, AND-gate, OR-gate, or XOR-gate, with 0, 1, or 2 inverted inputs. The logic used to implement these functions is shown in the upper gray area of Figure 17.

When configured as a multiplexer, this feature allows two output signals to time-share the same output pad; effectively doubling the number of device outputs without requiring a larger, more expensive package.

When the MUX is configured as a 2-input function generator, logic can be implemented within the IOB itself. Combined with a Global Early buffer, this arrangement allows very high-speed gating of a single signal. For example, a wide decoder can be implemented in CLBs, and its output gated with a Read or Write Strobe Driven by a BUFGE buffer, as shown in Figure 20. The critical-path pin-to-pin delay of this circuit is less than 6 nanoseconds.

As shown in Figure 17, the IOB input pins Out, Output Clock, and Clock Enable have different delays and different flexibilities regarding polarity. Additionally, Output Clock sources are more limited than the other inputs. Therefore, the Xilinx software does not move logic into the IOB function generators unless explicitly directed to do so.

The user can specify that the IOB function generator be used, by placing special library symbols beginning with the letter “O.” For example, a 2-input AND-gate in the IOB function generator is called OAND2. Use the symbol input pin labelled “F” for the signal on the critical path. This signal is placed on the OK pin — the IOB input with the shortest delay to the function generator. Two examples are shown in Figure 21.

---

Other IOB Options

There are a number of other programmable options in the XC4000 Series IOB.

Pull-up and Pull-down Resistors

Programmable pull-up and pull-down resistors are useful for tying unused pins to Vcc or Ground to minimize power consumption and reduce noise sensitivity. The configurable pull-up resistor is a p-channel transistor that pulls to Vcc. The configurable pull-down resistor is an n-channel transistor that pulls to Ground.

The value of these resistors is 50 kΩ – 100 kΩ. This high value makes them unsuitable as wired-AND pull-up resistors.

The pull-up resistors for most user-programmable IOBs are active during the configuration process. See Table 23 on page 4-58 for a list of pins with pull-ups active before and during configuration.

After configuration, voltage levels of unused pads, bonded or unbonded, must be valid logic levels, to reduce noise sensitivity and avoid excess current. Therefore, by default, unused pads are configured with the internal pull-up resistor active. Alternatively, they can be individually configured with the pull-down resistor, or as a driven output, or to be driven by an external source. To activate the internal pull-up, attach the PULLUP library component to the net attached to the pad. To activate the internal pull-down, attach the PULLDOWN library component to the net attached to the pad.

Independent Clocks

Separate clock signals are provided for the input and output flip-flops. The clock can be independently inverted for each flip-flop within the IOB, generating either falling-edge or rising-edge triggered flip-flops. The clock inputs for each IOB are independent, except that in the XC4000X, the Fast Capture latch shares an IOB input with the output clock pin.

Early Clock for IOBs (XC4000X only)

Special early clocks are available for IOBs. These clocks are sourced by the same sources as the Global Low-Skew buffers, but are separately buffered. They have fewer loads and therefore less delay. The early clock can drive either the IOB output clock or the IOB input clock, or both. The early clock allows fast capture of input data, and fast clock-to-output on output data. The Global Early buffers that drive these clocks are described in “Global Nets and Buffers (XC4000X only)” on page 4-38.

Global Set/Reset

As with the CLB registers, the Global Set/Reset signal (GSR) can be used to set or clear the input and output registers, depending on the value of the INIT attribute or property. The two flip-flops can be individually configured to set
or clear on reset and after configuration. Other than the global GSR net, no user-controlled set/reset signal is available to the I/O flip-flops. The choice of set or clear applies to both the initial state of the flip-flop and the response to the Global Set/Reset pulse. See “Global Set/Reset” on page 4-11 for a description of how to use GSR.

**JTAG Support**

Embedded logic attached to the IOBs contains test structures compatible with IEEE Standard 1149.1 for boundary scan testing, permitting easy chip and board-level testing. More information is provided in “Boundary Scan” on page 4-43.

**Three-State Buffers**

A pair of 3-state buffers is associated with each CLB in the array. (See Figure 28 on page 4-31.) These 3-state buffers can be used to drive signals onto the nearest horizontal longlines above and below the CLB. They can therefore be used to implement multiplexed or bidirectional buses on the horizontal longlines, saving logic resources. Programmable pull-up resistors attached to these longlines help to implement a wide wired-AND function.

The buffer enable is an active-High 3-state (i.e. an active-Low enable), as shown in Table 14.

Another 3-state buffer with similar access is located near each I/O block along the right and left edges of the array. (See Figure 34 on page 4-35.) The horizontal longlines driven by the 3-state buffers have a weak keeper at each end. This circuit prevents undefined floating levels. However, it is overridden by any driver, even a pull-up resistor.

Special longlines running along the perimeter of the array can be used to wire-AND signals coming from nearby IOBs or from internal longlines. These longlines form the wide edge decoders discussed in “Wide Edge Decoders” on page 4-28.

**Three-State Buffer Modes**

The 3-state buffers can be configured in three modes:

- Standard 3-state buffer
- Wired-AND with input on the I pin
- Wired OR-AND

**Standard 3-State Buffer**

All three pins are used. Place the library element BUFT. Connect the input to the I pin and the output to the O pin. The T pin is an active-High 3-state (i.e. an active-Low enable). Tie the T pin to Ground to implement a standard buffer.

**Wired-AND with Input on the I Pin**

The buffer can be used as a Wired-AND. Use the WAND1 library symbol, which is essentially an open-drain buffer. WAND4, WAND8, and WAND16 are also available. See the XACT Libraries Guide for further information.

The T pin is internally tied to the I pin. Connect the input to the I pin and the output to the O pin. Connect the outputs of all the WAND1s together and attach a PULLUP symbol.

**Wired OR-AND**

The buffer can be configured as a Wired OR-AND. A High level on either input turns off the output. Use the WOR2AND library symbol, which is essentially an open-drain 2-input OR gate. The two input pins are functionally equivalent. Attach the two inputs to the I0 and I1 pins and tie the output to the O pin. Tie the outputs of all the WOR2ANDs together and attach a PULLUP symbol.

**Three-State Buffer Examples**

Figure 22 shows how to use the 3-state buffers to implement a wired-AND function. When all the buffer inputs are High, the pull-up resistor(s) provide the High output.

Figure 23 shows how to use the 3-state buffers to implement a multiplexer. The selection is accomplished by the buffer 3-state signal.

Pay particular attention to the polarity of the T pin when using these buffers in a design. Active-High 3-state (T) is identical to an active-Low output enable, as shown in Table 14.

**Table 14: Three-State Buffer Functionality**

<table>
<thead>
<tr>
<th>IN</th>
<th>T</th>
<th>OUT</th>
</tr>
</thead>
<tbody>
<tr>
<td>X</td>
<td>1</td>
<td>Z</td>
</tr>
<tr>
<td>IN</td>
<td>0</td>
<td>IN</td>
</tr>
</tbody>
</table>

Figure 22: Open-Drain Buffers Implement a Wired-AND Function
Wide Edge Decoders

Dedicated decoder circuitry boosts the performance of wide decoding functions. When the address or data field is wider than the function generator inputs, FPGAs need multi-level decoding and are thus slower than PALs. XC4000 Series CLBs have nine inputs. Any decoder of up to nine inputs is, therefore, compact and fast. However, there is also a need for much wider decoders, especially for address decoding in large microprocessor systems.

An XC4000 Series FPGA has four programmable decoders located on each edge of the device. The inputs to each decoder are any of the IOB I1 signals on that edge plus one local interconnect per CLB row or column. Each row or column of CLBs provides up to three variables or their complements, as shown in Figure 24. Each decoder generates a High output (resistor pull-up) when the AND condition of the selected inputs, or their complements, is true. This is analogous to a product term in typical PAL devices.

Each of these wired-AND gates is capable of accepting up to 42 inputs on the XC4005E and 72 on the XC4013E. There are up to 96 inputs for each decoder on the XC4028X and 132 on the XC4052X. The decoders may also be split in two when a larger number of narrower decoders are required, for a maximum of 32 decoders per device.

The decoder outputs can drive CLB inputs, so they can be combined with other logic to form a PAL-like AND/OR structure. The decoder outputs can also be routed directly to the chip outputs. For fastest speed, the output should be on the same chip edge as the decoder. Very large PALs can be emulated by ORing the decoder outputs in a CLB. This decoding feature covers what has long been considered a weakness of older FPGAs. Users often resorted to external PALs for simple but fast decoding functions. Now, the dedicated decoders in the XC4000 Series device can implement these functions fast and efficiently.

To use the wide edge decoders, place one or more of the WAND library symbols (WAND1, WAND4, WAND8, WAND16). Attach a DECODE attribute or property to each WAND symbol. Tie the outputs together and attach a PUL-

Tie the outputs together and attach a PUL-

LUP symbol. Location attributes or properties such as L (left edge) or TR (right half of top edge) should also be used to ensure the correct placement of the decoder inputs.

On-Chip Oscillator

XC4000 Series devices include an internal oscillator. This oscillator is used to clock the power-on time-out, for configuration memory clearing, and as the source of CCLK in Master configuration modes. The oscillator runs at a nominal 8 MHz frequency that varies with process, Vcc, and temperature. The output frequency falls between 4 and 10 MHz.
The oscillator output is optionally available after configuration. Any two of four resynchronized taps of a built-in divider are also available. These taps are at the fourth, ninth, fourteenth and nineteenth bits of the divider. Therefore, if the primary oscillator output is running at the nominal 8 MHz, the user has access to an 8 MHz clock, plus any two of 500 kHz, 16 kHz, 490 Hz and 15 Hz (up to 10% lower for low-voltage devices). These frequencies can vary by as much as -50% or +25%.

These signals can be accessed by placing the OSC4 library element in a schematic or in HDL code (see Figure 25).

The oscillator is automatically disabled after configuration if the OSC4 symbol is not used in the design.

**Programmable Interconnect**

All internal connections are composed of metal segments with programmable switching points and switching matrices to implement the desired routing. A structured, hierarchical matrix of routing resources is provided to achieve efficient automated routing.

The XC4000E and XC4000X share a basic interconnect structure. XC4000X devices, however, have additional routing not available in the XC4000E. The extra routing resources allow high utilization in high-capacity devices. All XC4000X-specific routing resources are clearly identified throughout this section. Any resources not identified as XC4000X-specific are present in all XC4000 Series devices.

This section describes the varied routing resources available in XC4000 Series devices. The implementation software automatically assigns the appropriate resources based on the density and timing requirements of the design.

**Interconnect Overview**

There are several types of interconnect.

- **CLB routing** is associated with each row and column of the CLB array.
- **IOB routing** forms a ring (called a VersaRing) around the outside of the CLB array. It connects the I/O with the internal logic blocks.
- **Global routing** consists of dedicated networks primarily designed to distribute clocks throughout the device with minimum delay and skew. Global routing can also be used for other high-fanout signals.

Five interconnect types are distinguished by the relative length of their segments: single-length lines, double-length lines, quad and octal lines (XC4000X only), and longlines. In the XC4000X, direct connects allow fast data flow between adjacent CLBs, and between IOBs and CLBs.

Extra routing is included in the IOB pad ring. The XC4000X also includes a ring of octal interconnect lines near the IOBs to improve pin-swapping and routing to locked pins.

XC4000E/X devices include two types of global buffers. These global buffers have different properties, and are intended for different purposes. They are discussed in detail later in this section.

**CLB Routing Connections**

A high-level diagram of the routing resources associated with one CLB is shown in Figure 26. The shaded arrows represent routing present only in XC4000X devices.

Table 15 shows how much routing of each type is available in XC4000E and XC4000X CLB arrays. Clearly, very large designs, or designs with a great deal of interconnect, will route more easily in the XC4000X. Smaller XC4000E designs, typically requiring significantly less interconnect, do not require the additional routing.

Figure 28 on page 4-31 is a detailed diagram of both the XC4000E and the XC4000X CLB, with associated routing. The shaded square is the programmable switch matrix, present in both the XC4000E and the XC4000X. The L-shaped shaded area is present only in XC4000X devices. As shown in the figure, the XC4000X block is essentially an XC4000E block with additional routing.

CLB inputs and outputs are distributed on all four sides, providing maximum routing flexibility. In general, the entire architecture is symmetrical and regular. It is well suited to established placement and routing algorithms. Inputs, outputs, and function generators can freely swap positions within a CLB to avoid routing congestion during the placement and routing operation.
The horizontal and vertical single- and double-length lines intersect at a box called a programmable switch matrix (PSM). Each switch matrix consists of programmable pass transistors used to establish connections between the lines (see Figure 27).

For example, a single-length signal entering on the right side of the switch matrix can be routed to a single-length line on the top, left, or bottom sides, or any combination thereof, if multiple branches are required. Similarly, a double-length signal can be routed to a double-length line on any or all of the other three edges of the programmable switch matrix.

### Programmable Switch Matrices

The horizontal and vertical single- and double-length lines intersect at a box called a programmable switch matrix (PSM). Each switch matrix consists of programmable pass transistors used to establish connections between the lines (see Figure 27).

For example, a single-length signal entering on the right side of the switch matrix can be routed to a single-length line on the top, left, or bottom sides, or any combination thereof, if multiple branches are required. Similarly, a double-length signal can be routed to a double-length line on any or all of the other three edges of the programmable switch matrix.

### Single-Length Lines

Single-length lines provide the greatest interconnect flexibility and offer fast routing between adjacent blocks. There are eight vertical and eight horizontal single-length lines associated with each CLB. These lines connect the switching matrices that are located in every row and a column of CLBs.

Single-length lines are connected by way of the programmable switch matrices, as shown in Figure 29. Routing connectivity is shown in Figure 28.

Single-length lines incur a delay whenever they go through a switching matrix. Therefore, they are not suitable for routing signals for long distances. They are normally used to conduct signals within a localized area and to provide the branching for nets with fanout greater than one.
Common to XC4000E and XC4000X
XC4000X only
Programmable Switch Matrix

Figure 28: Detail of Programmable Interconnect Associated with XC4000 Series CLB
Double-Length Lines

The double-length lines consist of a grid of metal segments, each twice as long as the single-length lines: they run past two CLBs before entering a switch matrix. Double-length lines are grouped in pairs with the switch matrices staggered, so that each line goes through a switch matrix at every other row or column of CLBs (see Figure 29).

There are four vertical and four horizontal double-length lines associated with each CLB. These lines provide faster signal routing over intermediate distances, while retaining routing flexibility. Double-length lines are connected by way of the programmable switch matrices. Routing connectivity is shown in Figure 28.

Quad Lines (XC4000X only)

XC4000X devices also include twelve vertical and twelve horizontal quad lines per CLB row and column. Quad lines are four times as long as the single-length lines. They are interconnected via buffered switch matrices (shown as diamonds in Figure 28 on page 4-31). Quad lines run past four CLBs before entering a buffered switch matrix. They are grouped in fours, with the buffered switch matrices staggered, so that each line goes through a buffered switch matrix at every fourth CLB location in that row or column. (See Figure 30.)

The buffered switch matrixes have four pins, one on each edge. All of the pins are bidirectional. Any pin can drive any or all of the other pins.

Each buffered switch matrix contains one buffer and six pass transistors. It resembles the programmable switch matrix shown in Figure 27, with the addition of a programmable buffer. There can be up to two independent inputs and up to two independent outputs. Only one of the independent inputs can be buffered.

The place and route software automatically uses the timing requirements of the design to determine whether or not a quad line signal should be buffered. A heavily loaded signal is typically buffered, while a lightly loaded one is not. One scenario is to alternate buffers and pass transistors. This allows both vertical and horizontal quad lines to be buffered at alternating buffered switch matrices.

Due to the buffered switch matrices, quad lines are very fast. They provide the fastest available method of routing heavily loaded signals for long distances across the device.

Longlines

Longlines form a grid of metal interconnect segments that run the entire length or width of the array. Longlines are intended for high fan-out, time-critical signal nets, or nets that are distributed over long distances. In XC4000X devices, quad lines are preferred for critical nets, because the buffered switch matrices make them faster for high fan-out nets.

Two horizontal longlines per CLB can be driven by 3-state or open-drain drivers (TBUFs). They can therefore implement unidirectional or bidirectional buses, wide multiplexers, or wired-AND functions. (See “Three-State Buffers” on page 4-27 for more details.)

Each horizontal longline driven by TBUFs has either two (XC4000E) or eight (XC4000X) pull-up resistors. To activate these resistors, attach a PULLUP symbol to the longline net. The software automatically activates the appropriate number of pull-ups. There is also a weak keeper at each end of these two horizontal longlines. This circuit pre-
vents undefined floating levels. However, it is overridden by any driver, even a pull-up resistor.

Each XC4000E longline has a programmable splitter switch at its center, as does each XC4000X longline driven by TBUFs. This switch can separate the line into two independent routing channels, each running half the width or height of the array.

Each XC4000X longline not driven by TBUFs has a buffered programmable splitter switch at the 1/4, 1/2, and 3/4 points of the array. Due to the buffering, XC4000X longline performance does not deteriorate with the larger array sizes. If the longline is split, the resulting partial longlines are independent.

Routing connectivity of the longlines is shown in Figure 28 on page 4-31.

**Direct Interconnect (XC4000X only)**

The XC4000X offers two direct, efficient and fast connections between adjacent CLBs. These nets facilitate a data flow from the left to the right side of the device, or from the top to the bottom, as shown in Figure 31. Signals routed on the direct interconnect exhibit minimum interconnect propagation delay and use no general routing resources.

The direct interconnect is also present between CLBs and adjacent IOBs. Each IOB on the left and top device edges has a direct path to the nearest CLB. Each CLB on the right and bottom edges of the array has a direct path to the nearest two IOBs, since there are two IOBs for each row or column of CLBs.

The place and route software uses direct interconnect whenever possible, to maximize routing resources and minimize interconnect delays.

**I/O Routing**

XC4000 Series devices have additional routing around the IOB ring. This routing is called a VersaRing. The VersaRing facilitates pin-swapping and redesign without affecting board layout. Included are eight double-length lines spanning two CLBs (four IOBs), and four longlines. Global lines and Wide Edge Decoder lines are provided. XC4000X devices also include eight octal lines.

A high-level diagram of the VersaRing is shown in Figure 32. The shaded arrows represent routing present only in XC4000X devices.

Figure 34 on page 4-35 is a detailed diagram of the XC4000E and XC4000X VersaRing. The area shown includes two IOBs. There are two IOBs per CLB row or column, therefore this diagram corresponds to the CLB routing diagram shown in Figure 28 on page 4-31. The shaded areas represent routing and routing connections present only in XC4000X devices.

**Octal I/O Routing (XC4000X only)**

Between the XC4000X CLB array and the pad ring, eight interconnect tracks provide for versatility in pin assignment and fixed pinout flexibility. (See Figure 33 on page 4-34.)

These routing tracks are called octals, because they can be broken every eight CLBs (sixteen IOBs) by a programmable buffer that also functions as a splitter switch. The buffers are staggered, so each line goes through a buffer at every eighth CLB location around the device edge.

The octal lines bend around the corners of the device. The lines cross at the corners in such a way that the segment most recently buffered before the turn has the farthest distance to travel before the next buffer, as shown in Figure 33.
Figure 32: High-Level Routing Diagram of XC4000 Series VersaRing (Left Edge)
WED = Wide Edge Decoder, IOB = I/O Block (shaded arrows indicate XC4000X only)

Figure 33: XC4000X Octal I/O Routing
Figure 34: Detail of Programmable Interconnect Associated with XC4000 Series IOB (Left Edge)
IOB inputs and outputs interface with the octal lines via the single-length interconnect lines. Single-length lines are also used for communication between the octals and double-length lines, quads, and longlines within the CLB array.

Segmentation into buffered octals was found to be optimal for distributing signals over long distances around the device.

**Global Nets and Buffers**

Both the XC4000E and the XC4000X have dedicated global networks. These networks are designed to distribute clocks and other high fanout control signals throughout the devices with minimal skew. The global buffers are described in detail in the following sections. The text descriptions and diagrams are summarized in Table 16. The table shows which CLB and IOB clock pins can be sourced by which global buffers.

In both XC4000E and XC4000X devices, placement of a library symbol called BUFG results in the software choosing the appropriate clock buffer, based on the timing requirements of the design. The detailed information in these sections is included only for reference.

**Global Nets and Buffers (XC4000E only)**

Four vertical longlines in each CLB column are driven exclusively by special global buffers. These longlines are in addition to the vertical longlines used for standard interconnect. The four global lines can be driven by either of two types of global buffers. The clock pins of every CLB and IOB can also be sourced from local interconnect.

Two different types of clock buffers are available in the XC4000E:

- **Primary Global Buffers (BUFGP)**
- **Secondary Global Buffers (BUFGS)**

Four Primary Global buffers offer the shortest delay and negligible skew. Four Secondary Global buffers have slightly longer delay and slightly more skew due to potentially heavier loading, but offer greater flexibility when used to drive non-clock CLB inputs.

The Primary Global buffers must be driven by the semi-dedicated pads. The Secondary Global buffers can be sourced by either semi-dedicated pads or internal nets.

Each CLB column has four dedicated vertical Global lines. Each of these lines can be accessed by one particular Primary Global buffer, or by any of the Secondary Global buffers, as shown in Figure 35. Each corner of the device has one Primary buffer and one Secondary buffer.

IOBs along the left and right edges have four vertical global longlines. Top and bottom IOBs can be clocked from the global lines in the adjacent CLB column.

A global buffer should be specified for all timing-sensitive global signal distribution. To use a global buffer, place a BUFGP (primary buffer), BUFGS (secondary buffer), or BUFG (either primary or secondary buffer) element in a schematic or in HDL code. If desired, attach a LOC attribute or property to direct placement to the designated location. For example, attach a LOC=L attribute or property to a BUFGS symbol to direct that a buffer be placed in one of the two Secondary Global buffers on the left edge of the device, or a LOC=BL to indicate the Secondary Global buffer on the bottom edge of the device, on the left.

### Table 16: Clock Pin Access

<table>
<thead>
<tr>
<th></th>
<th>XC4000E BUFGP</th>
<th>XC4000E BUFGS</th>
<th>XC4000X BUFGLS</th>
<th>XC4000X L &amp; R BUFGE</th>
<th>XC4000X T &amp; B BUFGE</th>
<th>Local Interconnect</th>
</tr>
</thead>
<tbody>
<tr>
<td>All CLBs in Quadrant</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>All CLBs in Device</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>IOBs on Adjacent Vertical Half Edge</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>IOBs on Adjacent Vertical Full Edge</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>IOBs on Adjacent Horizontal Half Edge (Direct)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>IOBs on Adjacent Horizontal Half Edge (through CLB globals)</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
<tr>
<td>IOBs on Adjacent Horizontal Full Edge (through CLB globals)</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
<td>√</td>
</tr>
</tbody>
</table>

L = Left, R = Right, T = Top, B = Bottom

November 10, 1997 (Version 1.4)
Figure 35: XC4000E Global Net Distribution

Figure 36: XC4000X Global Net Distribution
**Global Nets and Buffers (XC4000X only)**

Eight vertical longlines in each CLB column are driven by special global buffers. These longlines are in addition to the vertical longlines used for standard interconnect. The global lines are broken in the center of the array, to allow faster distribution and to minimize skew across the whole array. Each half-column global line has its own buffered multiplexer, as shown in Figure 36. The top and bottom global lines cannot be connected across the center of the device, as this connection might introduce unacceptable skew. The top and bottom halves of the global lines must be separately driven — although they can be driven by the same global buffer.

The eight global lines in each CLB column can be driven by either of two types of global buffers. They can also be driven by internal logic, because they can be accessed by single, double, and quad lines at the top, bottom, half, and quarter points. Consequently, the number of different clocks that can be used simultaneously in an XC4000X device is very large.

There are four global lines feeding the IOBs at the left edge of the device. IOBs along the right edge have eight global lines. There is a single global line along the top and bottom edges with access to the IOBs. All IOB global lines are broken at the center. They cannot be connected across the center of the device, as this connection might introduce unacceptable skew.

IOB global lines can be driven from two types of global buffers, or from local interconnect. Alternatively, top and bottom IOBs can be clocked from the global lines in the adjacent CLB column.

Two different types of clock buffers are available in the XC4000X:

- Global Low-Skew Buffers (BUFGLS)
- Global Early Buffers (BUFGE)

Global Low-Skew Buffers are the standard clock buffers. They should be used for most internal clocking, whenever a large portion of the device must be driven.

Global Early Buffers are designed to provide a faster clock access, but CLB access is limited to one-fourth of the device. They also facilitate a faster I/O interface.

Figure 36 is a conceptual diagram of the global net structure in the XC4000X.

Global Early buffers and Global Low-Skew buffers share a single pad. Therefore, the same IPAD symbol can drive one buffer of each type, in parallel. This configuration is particularly useful when using the Fast Capture latches, as described in “IOB Input Signals” on page 4-21. Paired Global Early and Global Low-Skew buffers share a common input; they cannot be driven by two different signals.

**Choosing an XC4000X Clock Buffer**

The clocking structure of the XC4000X provides a large variety of features. However, it can be simple to use, without understanding all the details. The software automatically handles clocks, along with all other routing, when the appropriate clock buffer is placed in the design. In fact, if a buffer symbol called BUFG is placed, rather than a specific type of buffer, the software even chooses the buffer most appropriate for the design. The detailed information in this section is provided for those users who want a finer level of control over their designs.

If fine control is desired, use the following summary and Table 16 on page 4-36 to choose an appropriate clock buffer.

- The simplest thing to do is to use a Global Low-Skew buffer.
- If a faster clock path is needed, try a BUFG. The software will first try to use a Global Low-Skew Buffer. If timing requirements are not met, a faster buffer will automatically be used.
- If a single quadrant of the chip is sufficient for the clocked logic, and the timing requires a faster clock than the Global Low-Skew buffer, use a Global Early buffer.

**Global Low-Skew Buffers**

Each corner of the XC4000X device has two Global Low-Skew buffers. Any of the eight Global Low-Skew buffers can drive any of the eight vertical Global lines in a column of CLBs. In addition, any of the buffers can drive any of the four vertical lines accessing the IOBs on the left edge of the device, and any of the eight vertical lines accessing the IOBs on the right edge of the device. (See Figure 37 on page 4-39.)

IOBs at the top and bottom edges of the device are accessed through the vertical Global lines in the CLB array, as in the XC4000E. Any Global Low-Skew buffer can, therefore, access every IOB and CLB in the device.

The Global Low-Skew buffers can be driven by either semi-dedicated pads or internal logic.

To use a Global Low-Skew buffer, instantiate a BUFGLS element in a schematic or in HDL code. If desired, attach a LOC attribute or property to direct placement to the designated location. For example, attach a LOC=TR attribute or property to direct that a BUFGLS be placed in one of the two Global Low-Skew buffers on the top edge of the device, or a LOC=TR to indicate the Global Low-Skew buffer on the top edge of the device, on the right.
Global Early Buffers

Each corner of the XC4000X device has two Global Early buffers. The primary purpose of the Global Early buffers is to provide an earlier clock access than the potentially heavily-loaded Global Low-Skew buffers. A clock source applied to both buffers will result in the Global Early clock edge occurring several nanoseconds earlier than the Global Low-Skew buffer clock edge, due to the lighter loading.

Global Early buffers also facilitate the fast capture of device inputs, using the Fast Capture latches described in “IOB Input Signals” on page 4-21. For Fast Capture, take a single clock signal, and route it through both a Global Early buffer and a Global Low-Skew buffer. (The two buffers share an input pad.) Use the Global Early buffer to clock the Fast Capture latch, and the Global Low-Skew buffer to clock the normal input flip-flop or latch, as shown in Figure 18 on page 4-24.

The Global Early buffers can also be used to provide a fast Clock-to-Out on device output pins. However, an early clock in the output flip-flop IOB must be taken into consideration when calculating the internal clock speed for the design.

The Global Early buffers at the left and right edges of the chip have slightly different capabilities than the ones at the top and bottom. Refer to Figure 38, Figure 39, and Figure 36 on page 4-37 while reading the following explanation.

Each Global Early buffer can access the eight vertical Global lines for all CLBs in the quadrant. Therefore, only one-fourth of the CLB clock pins can be accessed. This restriction is in large part responsible for the faster speed of the buffers, relative to the Global Low-Skew buffers.

The left-side Global Early buffers can each drive two of the four vertical lines accessing the IOBs on the entire left edge of the device. The right-side Global Early buffers can each drive two of the eight vertical lines accessing the IOBs on the entire right edge of the device. (See Figure 38.) Each left and right Global Early buffer can also drive half of the IOBs along either the top or bottom edge of the device, using a dedicated line that can only be accessed through the Global Early buffers.

The top and bottom Global Early buffers can drive half of the IOBs along either the left or right edge of the device, as shown in Figure 39. They can only access the top and bottom IOBs via the CLB global lines.

Each Global Early buffer can access the eight vertical Global lines for all CLBs in the quadrant. Therefore, only one-fourth of the CLB clock pins can be accessed. This restriction is in large part responsible for the faster speed of the buffers, relative to the Global Low-Skew buffers.

The left-side Global Early buffers can each drive two of the four vertical lines accessing the IOBs on the entire left edge of the device. The right-side Global Early buffers can each drive two of the eight vertical lines accessing the IOBs on the entire right edge of the device. (See Figure 38.) Each left and right Global Early buffer can also drive half of the IOBs along either the top or bottom edge of the device, using a dedicated line that can only be accessed through the Global Early buffers.

The top and bottom Global Early buffers can drive half of the IOBs along either the left or right edge of the device, as shown in Figure 39. They can only access the top and bottom IOBs via the CLB global lines.
The top and bottom Global Early buffers are about 1 ns slower clock to out than the left and right Global Early buffers.

The Global Early buffers can be driven by either semi-dedicated pads or internal logic. They share pads with the Global Low-Skew buffers, so a single net can drive both global buffers, as described above.

To use a Global Early buffer, place a BUFGE element in a schematic or in HDL code. If desired, attach a LOC attribute or property to direct placement to the designated location. For example, attach a LOC=T attribute or property to direct that a BUFGE be placed in one of the two Global Early buffers on the top edge of the device, or a LOC=TR to indicate the Global Early buffer on the top edge of the device, on the right.

**Power Distribution**

Power for the FPGA is distributed through a grid to achieve high noise immunity and isolation between logic and I/O. Inside the FPGA, a dedicated Vcc and Ground ring surrounding the logic array provides power to the I/O drivers, as shown in Figure 40. An independent matrix of Vcc and Ground lines supplies the interior logic of the device.

This power distribution grid provides a stable supply and ground for all internal logic, providing the external package power pins are all connected and appropriately decoupled. Typically, a 0.1 µF capacitor connected between each Vcc pin and the board’s Ground plane will provide adequate decoupling.

Output buffers capable of driving/sinking the specified 12 mA loads under specified worst-case conditions may be capable of driving/sinking up to 10 times as much current under best case conditions.

Noise can be reduced by minimizing external load capacitance and reducing simultaneous output transitions in the same direction. It may also be beneficial to locate heavily loaded output buffers near the Ground pads. The I/O Block output buffers have a slew-rate limited mode (default) which should be used where output rise and fall times are not speed-critical.

![Figure 40: XC4000 Series Power Distribution](image)

**Pin Descriptions**

There are three types of pins in the XC4000 Series devices:

- Permanently dedicated pins
- User I/O pins that can have special functions
- Unrestricted user-programmable I/O pins.

Before and during configuration, all outputs not used for the configuration process are 3-stated with a 50 kΩ - 100 kΩ pull-up resistor.

After configuration, if an IOB is unused it is configured as an input with a 50 kΩ - 100 kΩ pull-up resistor.

XC4000 Series devices have no dedicated Reset input. Any user I/O can be configured to drive the Global Set/Reset net, GSR. See “Global Set/Reset” on page 4-11 for more information on GSR.

XC4000 Series devices have no Powerdown control input, as the XC3000 and XC2000 families do. The XC3000/ XC2000 Powerdown control also 3-stated all of the device I/O pins. For XC4000 Series devices, use the global 3-state net, GTS, instead. This net 3-states all outputs, but does not place the device in low-power mode. See “IOB Output Signals” on page 4-24 for more information on GTS.

Device pins for XC4000 Series devices are described in Table 17. Pin functions during configuration for each of the seven configuration modes are summarized in Table 23 on page 4-58, in the “Configuration Timing” section.
### Table 17: Pin Descriptions

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>I/O During Config.</th>
<th>I/O After Config.</th>
<th>Pin Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Permanently Dedicated Pins</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>VCC</td>
<td>I</td>
<td>I</td>
<td>Eight or more (depending on package) connections to the nominal +5 V supply voltage (+3.3 V for low-voltage devices). All must be connected, and each must be decoupled with a 0.01 - 0.1 µF capacitor to Ground.</td>
</tr>
<tr>
<td>GND</td>
<td>I</td>
<td>I</td>
<td>Eight or more (depending on package type) connections to Ground. All must be connected.</td>
</tr>
<tr>
<td>CCLK</td>
<td>I or O</td>
<td>I</td>
<td>During configuration, Configuration Clock (CCLK) is an output in Master modes or Asynchronous Peripheral mode, but is an input in Slave mode and Synchronous Peripheral mode. After configuration, CCLK has a weak pull-up resistor and can be selected as the Readback Clock. There is no CCLK High time restriction on XC4000 Series devices, except during Readback. See “Violating the Maximum High and Low Time Specification for the Readback Clock” on page 4-57 for an explanation of this exception.</td>
</tr>
<tr>
<td>DONE</td>
<td>I/O</td>
<td>O</td>
<td>DONE is a bidirectional signal with an optional internal pull-up resistor. As an output, it indicates the completion of the configuration process. As an input, a Low level on DONE can be configured to delay the global logic initialization and the enabling of outputs. The optional pull-up resistor is selected as an option in the XACTstep program that creates the configuration bitstream. The resistor is included by default.</td>
</tr>
<tr>
<td>PROGRAM</td>
<td>I</td>
<td>I</td>
<td>PROGRAM is an active Low input that forces the FPGA to clear its configuration memory. It is used to initiate a configuration cycle. When PROGRAM goes High, the FPGA finishes the current clear cycle and executes another complete clear cycle, before it goes into a WAIT state and releases INIT. The PROGRAM pin has a permanent weak pull-up, so it need not be externally pulled up to Vcc.</td>
</tr>
<tr>
<td><strong>User I/O Pins That Can Have Special Functions</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>RDY/BUSY</td>
<td>O</td>
<td>I/O</td>
<td>During Peripheral mode configuration, this pin indicates when it is appropriate to write another byte of data into the FPGA. The same status is also available on D7 in Asynchronous Peripheral mode, if a read operation is performed when the device is selected. After configuration, RDY/BUSY is a user-programmable I/O pin. RDY/BUSY is pulled High with a high-impedance pull-up prior to INIT going High.</td>
</tr>
<tr>
<td>RCLK</td>
<td>O</td>
<td>I/O</td>
<td>During Master Parallel configuration, each change on the A0-A17 outputs (A0 - A21 for XC4000X) is preceded by a rising edge on RCLK, a redundant output signal. RCLK is useful for clocked PROMs. It is rarely used during configuration. After configuration, RCLK is a user-programmable I/O pin.</td>
</tr>
<tr>
<td>M0, M1, M2</td>
<td>I</td>
<td>(M0), O (M1), I (M2)</td>
<td>As Mode inputs, these pins are sampled after INIT goes High to determine the configuration mode to be used. After configuration, M0 and M2 can be used as inputs, and M1 can be used as a 3-state output. These three pins have no associated input or output registers. During configuration, these pins have weak pull-up resistors. For the most popular configuration mode, Slave Serial, the mode pins can thus be left unconnected. The three mode inputs can be individually configured with or without weak pull-up or pull-down resistors. A pull-down resistor value of 4.7 kΩ is recommended. These pins can only be used as inputs or outputs when called out by special schematic definitions. To use these pins, place the library components MD0, MD1, and MD2 instead of the usual pad symbols. Input or output buffers must still be used.</td>
</tr>
<tr>
<td>TDO</td>
<td>O</td>
<td>O</td>
<td>If boundary scan is used, this pin is the Test Data Output. If boundary scan is not used, this pin is a 3-state output without a register, after configuration is completed. This pin can be user output only when called out by special schematic definitions. To use this pin, place the library component TDO instead of the usual pad symbol. An output buffer must still be used.</td>
</tr>
</tbody>
</table>
Table 17: Pin Descriptions (Continued)

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>I/O During Config.</th>
<th>I/O After Config.</th>
<th>Pin Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TDI, TCK, TMS</td>
<td>I</td>
<td>I/O or I (JTAG)</td>
<td>If boundary scan is used, these pins are Test Data In, Test Clock, and Test Mode Select inputs respectively. They come directly from the pads, bypassing the IOBs. These pins can also be used as inputs to the CLB logic after configuration is completed. If the BSCAN symbol is not placed in the design, all boundary scan functions are inhibited once configuration is completed, and these pins become user-programmable I/O. In this case, they must be called out by special schematic definitions. To use these pins, place the library components TDI, TCK, and TMS instead of the usual pad symbols. Input or output buffers must still be used.</td>
</tr>
<tr>
<td>HDC</td>
<td>O</td>
<td>I/O</td>
<td>High During Configuration (HDC) is driven High until the I/O go active. It is available as a control output indicating that configuration is not yet completed. After configuration, HDC is a user-programmable I/O pin.</td>
</tr>
<tr>
<td>LDC</td>
<td>O</td>
<td>I/O</td>
<td>Low During Configuration (LDC) is driven Low until the I/O go active. It is available as a control output indicating that configuration is not yet completed. After configuration, LDC is a user-programmable I/O pin.</td>
</tr>
<tr>
<td>INIT</td>
<td>I/O</td>
<td>I/O</td>
<td>Before and during configuration, INIT is a bidirectional signal. A 1 kΩ - 10 kΩ external pull-up resistor is recommended. As an active-Low open-drain output, INIT is held Low during the power stabilization and internal clearing of the configuration memory. As an active-Low input, it can be used to hold the FPGA in the internal WAIT state before the start of configuration. Master mode devices stay in a WAIT state an additional 30 to 300 μs after INIT has gone High. During configuration, a Low on this output indicates that a configuration data error has occurred. After the I/O go active, INIT is a user-programmable I/O pin.</td>
</tr>
<tr>
<td>PGCK1 - PGCK4</td>
<td>Weak Pull-up</td>
<td>I or I/O</td>
<td>Four Primary Global inputs each drive a dedicated internal global net with short delay and minimal skew. If not used to drive a global buffer, any of these pins is a user-programmable I/O. The PGCK1-PGCK4 pins drive the four Primary Global Buffers. Any input pad symbol connected directly to the input of a BUFGP symbol is automatically placed on one of these pins.</td>
</tr>
<tr>
<td>SGCK1 - SGCK4</td>
<td>Weak Pull-up</td>
<td>I or I/O</td>
<td>Four Secondary Global inputs each drive a dedicated internal global net with short delay and minimal skew. These internal global nets can also be driven from internal logic. If not used to drive a global net, any of these pins is a user-programmable I/O pin. The SGCK1-SGCK4 pins provide the shortest path to the four Secondary Global Buffers. Any input pad symbol connected directly to the input of a BUFGS symbol is automatically placed on one of these pins.</td>
</tr>
<tr>
<td>GCK1 - GCK8</td>
<td>Weak Pull-up</td>
<td>I or I/O</td>
<td>Eight inputs can each drive a Global Low-Skew buffer. In addition, each can drive a Global Early buffer. Each pair of global buffers can also be driven from internal logic, but must share an input signal. If not used to drive a global buffer, any of these pins is a user-programmable I/O. Any input pad symbol connected directly to the input of a BUFGLS or BUFGE symbol is automatically placed on one of these pins.</td>
</tr>
<tr>
<td>CS0, CS1, WS, RS</td>
<td>I</td>
<td>I/O</td>
<td>These four inputs are used in Asynchronous Peripheral mode. The chip is selected when CS0 is Low and CS1 is High. While the chip is selected, a Low on Write Strobe (WS) loads the data present on the D0 - D7 inputs into the internal data buffer. A Low on Read Strobe (RS) changes D7 into a status output — High if Ready, Low if Busy — and drives D0 - D6 High. In Express mode, CS1 is used as a serial-enable signal for daisy-chaining. WS and RS should be mutually exclusive, but if both are Low simultaneously, the Write Strobe overrides. After configuration, these are user-programmable I/O pins.</td>
</tr>
<tr>
<td>A0 - A17</td>
<td>O</td>
<td>I/O</td>
<td>During Master Parallel configuration, these 18 output pins address the configuration EPROM. After configuration, they are user-programmable I/O pins.</td>
</tr>
</tbody>
</table>
Boundary Scan

The ‘bed of nails’ has been the traditional method of testing electronic assemblies. This approach has become less appropriate, due to closer pin spacing and more sophisticated assembly methods like surface-mount technology and multi-layer boards. The IEEE Boundary Scan Standard 1149.1 was developed to facilitate board-level testing of electronic assemblies. Design and test engineers can embed a standard test logic structure in their device to achieve high fault coverage for I/O and internal logic. This structure is easily implemented with a four-pin interface on any boundary scan-compatible IC. IEEE 1149.1-compatible devices may be serial daisy-chained together, connected in parallel, or a combination of the two.

The XC4000 Series implements IEEE 1149.1-compatible BYPASS, PRELOAD/SAMPLE and EXTEST boundary scan instructions. When the boundary scan configuration option is selected, three normal user I/O pins become dedicated inputs for these functions. Another user output pin becomes the dedicated boundary scan output. The details of how to enable this circuitry are covered later in this section.

By exercising these input signals, the user can serially load commands and data into these devices to control the driving of their outputs and to examine their inputs. This method is an improvement over bed-of-nails testing. It avoids the need to over-drive device outputs, and it reduces the user interface to four pins. An optional fifth pin, a reset for the control logic, is described in the standard but is not implemented in Xilinx devices.

The dedicated on-chip logic implementing the IEEE 1149.1 functions includes a 16-state machine, an instruction register and a number of data registers. The functional details can be found in the IEEE 1149.1 specification and are also discussed in the Xilinx application note XAPP 017: “Boundary Scan in XC4000 Devices.”

Figure 41 on page 4-44 shows a simplified block diagram of the XC4000E Input/Output Block with boundary scan implemented. XC4000X boundary scan logic is identical. Figure 42 on page 4-45 is a diagram of the XC4000 Series boundary scan logic. It includes three bits of Data Register per IOB, the IEEE 1149.1 Test Access Port controller, and the Instruction Register with decodes.

XC4000 Series devices can also be configured through the boundary scan logic. See “Readback” on page 4-56.

Data Registers

The primary data register is the boundary scan register. For each IOB pin in the FPGA, bonded or not, it includes three bits for In, Out and 3-State Control. Non-IOB pins have appropriate partial bit population for In or Out only. PROGRAM, CCLK and DONE are not included in the boundary scan register. Each EXTEST CAPTURE-DR state captures all In, Out, and 3-state pins.

The data register also includes the following non-pin bits: TDO.T, and TDO.O, which are always bits 0 and 1 of the data register, respectively, and BSCANT.UPD, which is

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>I/O During Config.</th>
<th>I/O After Config.</th>
<th>Pin Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>A18 - A21</td>
<td>O</td>
<td>I/O</td>
<td>During Master Parallel configuration with an XC4000X master, these 4 output pins add 4 more bits to address the configuration EPROM. After configuration, they are user-programmable I/O pins. (See Master Parallel Configuration section for additional details.)</td>
</tr>
<tr>
<td>D0 - D7</td>
<td>I</td>
<td>I/O</td>
<td>During Master Parallel and Peripheral configuration, these eight input pins receive configuration data. After configuration, they are user-programmable I/O pins.</td>
</tr>
<tr>
<td>DIN</td>
<td>I</td>
<td>I/O</td>
<td>During Slave Serial or Master Serial configuration, DIN is the serial configuration data input receiving data on the rising edge of CCLK. During Parallel configuration, DIN is the D0 input. After configuration, DIN is a user-programmable I/O pin.</td>
</tr>
<tr>
<td>DOUT</td>
<td>O</td>
<td>I/O</td>
<td>During configuration in any mode but Express mode, DOUT is the serial configuration data output that can drive the DIN of daisy-chained slave FPGAs. DOUT data changes on the falling edge of CCLK, one-and-a-half CCLK periods after it was received at the DIN input. In Express mode, DOUT is the status output that can drive the CS1 of daisy-chained FPGAs, to enable and disable downstream devices. After configuration, DOUT is a user-programmable I/O pin.</td>
</tr>
</tbody>
</table>

Unrestricted User-Programmable I/O Pins

<table>
<thead>
<tr>
<th>I/O Weak Pull-up</th>
<th>I/O</th>
</tr>
</thead>
<tbody>
<tr>
<td>These pins can be configured to be input and/or output after configuration is completed. Before configuration is completed, these pins have an internal high-value pull-up resistor (25 k(\Omega) - 100 k(\Omega)) that defines the logic level as High.</td>
<td></td>
</tr>
</tbody>
</table>
always the last bit of the data register. These three boundary scan bits are special-purpose Xilinx test signals.

The other standard data register is the single flip-flop BYPASS register. It synchronizes data being passed through the FPGA to the next downstream boundary scan device.

The FPGA provides two additional data registers that can be specified using the BSCAN macro. The FPGA provides two user pins (BSCAN.SEL1 and BSCAN.SEL2) which are the decodes of two user instructions. For these instructions, two corresponding pins (BSCAN.TDO1 and BSCAN.TDO2) allow user scan data to be shifted out on TDO. The data register clock (BSCAN.DRCK) is available for control of test logic which the user may wish to implement with CLBs. The NAND of TCK and RUN-TEST-IDLE is also provided (BSCAN.IDLE).

Figure 41: Block Diagram of XC4000E IOB with Boundary Scan (some details not shown). XC4000X Boundary Scan Logic is Identical.
Instruction Set

The XC4000 Series boundary scan instruction set also includes instructions to configure the device and read back the configuration data. The instruction set is coded as shown in Table 18.

Bit Sequence

The bit sequence within each IOB is: In, Out, 3-State. The input-only M0 and M2 mode pins contribute only the In bit to the boundary scan I/O data register, while the output-only M1 pin contributes all three bits.

The first two bits in the I/O data register are TDO.T and TDO.O, which can be used for the capture of internal signals. The final bit is BSCANT.UPD, which can be used to drive an internal net. These locations are primarily used by Xilinx for internal testing.

From a cavity-up view of the chip (as shown in XDE or Epic), starting in the upper right chip corner, the boundary scan data-register bits are ordered as shown in Figure 43. The device-specific pinout tables for the XC4000 Series include the boundary scan locations for each IOB pin.

BSDL (Boundary Scan Description Language) files for XC4000 Series devices are available on the Xilinx FTP site.

Including Boundary Scan in a Schematic

If boundary scan is only to be used during configuration, no special schematic elements need be included in the schematic or HDL code. In this case, the special boundary scan pins TDI, TMS, TCK and TDO can be used for user functions after configuration.

To indicate that boundary scan remain enabled after configuration, place the BSCAN library symbol and connect the TDI, TMS, TCK and TDO pad symbols to the appropriate pins, as shown in Figure 44.

Even if the boundary scan symbol is used in a schematic, the input pins TMS, TCK, and TDI can still be used as inputs to be routed to internal logic. Care must be taken not to force the chip into an undesired boundary scan state by inadvertently applying boundary scan input patterns to these pins. The simplest way to prevent this is to keep TMS High, and then apply whatever signal is desired to TDI and TCK.
Table 18: Boundary Scan Instructions

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Test Selected</th>
<th>TDO Source</th>
<th>I/O Data Source</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>EXTEST</td>
<td>DR</td>
<td>DR</td>
</tr>
<tr>
<td>0 0 1</td>
<td>SAMPLE/ PRELOAD</td>
<td>DR</td>
<td>Pin/Logic</td>
</tr>
<tr>
<td>0 1 0</td>
<td>USER 1</td>
<td>BSCAN, TDO1</td>
<td>User Logic</td>
</tr>
<tr>
<td>0 1 1</td>
<td>USER 2</td>
<td>BSCAN, TDO2</td>
<td>User Logic</td>
</tr>
<tr>
<td>1 0 0</td>
<td>READBACK</td>
<td>Readback Data</td>
<td>Pin/Logic</td>
</tr>
<tr>
<td>1 0 1</td>
<td>CONFIGURE</td>
<td>DOUT</td>
<td>Disabled</td>
</tr>
<tr>
<td>1 1 0</td>
<td>Reserved</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>1 1 1</td>
<td>BYPASS</td>
<td>Bypass Register</td>
<td>—</td>
</tr>
</tbody>
</table>

Avoiding Inadvertent Boundary Scan

If TMS or TCK is used as user I/O, care must be taken to ensure that at least one of these pins is held constant during configuration. In some applications, a situation may occur where TMS or TCK is driven during configuration. This may cause the device to go into boundary scan mode and disrupt the configuration process.

To prevent activation of boundary scan during configuration, do either of the following:

- TMS: Tie High to put the Test Access Port controller in a benign RESET state
- TCK: Tie High or Low—don’t toggle this clock input.

For more information regarding boundary scan, refer to the Xilinx Application Note XAPP 017.001, “Boundary Scan in XC4000E Devices.”

Figure 43: Boundary Scan Bit Sequence

Figure 44: Boundary Scan Schematic Example